Dynamics of vortex dipoles in confined Bose–Einstein condensates

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Abstract

We present a systematic theoretical analysis of the motion of a pair of straight counter-rotating vortex lines within a trapped Bose–Einstein condensate. We introduce the dynamical equations of motion, identify the associated conserved quantities, and illustrate the integrability of the ensuing dynamics. The system possesses a stationary equilibrium as a special case in a class of exact solutions that consist of rotating guiding-center equilibria about which the vortex lines execute periodic motion; thus, the generic two-vortex motion can be classified as quasi-periodic. We conclude with an analysis of the linear and nonlinear stability of these stationary and rotating equilibria.

1. Introduction

Vortices are persistent circulating flow patterns that occur in many diverse scientific and mathematical contexts [1], ranging from hydrodynamics, superfluids, and nonlinear optics to specific instantiations in sunspots, dust devils [2], and plant propulsion [3]. In atomic Bose–Einstein condensates (BECs) at ultracold temperatures [4–6], quantized vortices arise as especially persistent topological defects that play important roles in both Hamiltonian and dissipative dynamics, as well as in quantum turbulence. Vortices and vortex lattices in atomic BECs have been analyzed in a series of reviews [7–9].

Recently, much theoretical [10–17] and experimental [18–21] attention has been devoted to small vortex clusters, with a special focus on the simplest “vortex molecule”, the vortex dipole. This structure, consisting of two counter-circulating vortices, is central to the relaxation of superfluids through pairwise reconnection of the vortex lines. Such reconstructions have recently been observed in turbulent superfluid helium [22], a system considerably more complicated than the dilute-gas BEC.

Vortices in a Bose–Einstein condensate are observed experimentally by identification of the vortex lines (or “cores”), which are regions of reduced atomic density that surround the phase singularity about which the fluid rotates. The dynamics of the vortex lines in a dipole are, in general, three-dimensional (3D), and can be simulated through a mean-field model, namely the Gross–Pitaevskii partial differential equation (PDE) [18,23–26]. In many cases of experimental interest the vortex lines are straight and parallel, enabling calculations based on two-dimensional (2D) reductions of the PDEs. Such simulations have not proven entirely satisfactory in their agreement with recent experimental results [19,21]. An alternative 2D formulation is to focus on the dynamics of the vortex lines by evaluating an ordinary differential equation (ODE) that treats the locations of the lines as individual (quasi) particles [16,21]. The latter approach privileges the vortex lines themselves and enables considerable insight into their fundamental dynamics, even as the loss of the third dimension precludes a direct investigation of reconnection dynamics.

Our aim in the present work is to offer a systematic study of the equations of motion ensuing from the quasi-particle approach, focusing on an ODE model of two straight counter-circulating vortex lines in a cylindrically symmetric Bose–Einstein condensate. We calculate the conserved quantities and integrability of the model in the case of two vortices. The vortex lines therefore undergo generically quasi-periodic motion. To cement this observation, we present a comprehensive analysis of the system’s stationary and time-periodic states. We identify time-periodic guiding center solutions and explicitly compute their frequency as well as the fixed distances of their constituent vortex lines from the center of the superfluid. Finally, we examine both the linear and nonlinear stability of such states, arguing that the generic quasi-periodic motion of the two-vortex system consists of such guiding-center rotations along with (second frequency) epicycles around these states.
Our presentation is structured as follows. In Section 2, we present the mathematical model, while in Section 3, we examine its conserved quantities, integrability and associated dynamics. In Section 4 we consider the special stationary equilibrium, which we generalize to rotating, guiding-center equilibria in Section 5. Finally, we conclude our presentation in Section 6 with some interesting aspects of the problem for future study.

2. Model

We consider straight line vortices in a Bose–Einstein condensate with cylindrical symmetry. The most prominent physical example arises in the context of harmonically confined, oblate BECs [27], but the same general equations and conclusions may be drawn in the case of a hard-wall container as well [9]. We begin by considering an ensemble of singly-quantized vortices, and in the following section specialize to the case of the vortex dipole.

The motion of a vortex line involves its interactions with other vortex lines, as well as the effect of “boundary conditions” associated with the fluid confinement [16]. We begin with the interactions. The angular velocity of the fluid flow a distance \( r \) from a singly-quantized vortex core in a homogeneous fluid is

\[
\Phi (r) = \frac{\hbar}{mr^2},
\]

where \( m \) is the atomic mass. This flow pattern determines the motion of a second vortex line, which moves with the flow at its center (core) [28]. The motion of the first vortex line is similarly determined by the flow pattern established by the second. If the separation between the \( j \)th and \( k \)th vortex lines is \( r_{jk} \), then the two same-charge vortex lines orbit one another at angular frequency \( \Omega (r_{jk}) \). On the other hand, if the vortices are counter-circulating (vortices of opposite charge), then the vortex lines move together with linear speed \( v_{jk} = r_{jk} \Phi (r_{jk}) \) in the direction of the flow between them (Fig. 1a).

The motion of the \( k \)th vortex line in either a hard-wall or a disk-shaped harmonic potential also involves gyroscopic precession about the condensate center at fixed distance \( r_j \) (Fig. 1b). The precession frequency may be expressed in both cases by [7,9,19]

\[
\Omega (r_k) = \frac{\Omega_0}{1 - r_k^2/R^2},
\]

with

\[
\Omega_0 = \begin{cases} 
\frac{\hbar}{2mR^2} \frac{2k_0^2}{\omega_T^2} \left( 3 + \frac{\omega_T^2}{5k_0^2} \right) \ln \left( \frac{2r_k}{k_0} \right) & \text{hard-wall,} \\
\frac{\hbar}{4m} & \text{harmonic,}
\end{cases}
\]

where \( \mu \) is the chemical potential, \( \omega_T \) and \( \omega_P \) are the confining radial and axial frequencies of the harmonic trap, respectively, and \( R \) is the Thomas–Fermi radius of the condensate or the radius of the hard-wall cylinder [9]. The common dependence on \( r_k \) is what draws together these two different physical situations.

Summing these two velocities for the \( k \)th vortex in a “gas” of \( n \) vortices gives, in complex coordinates [21],

\[
i \dot{z}_k = -i \Omega (r_k) z_k + \frac{\hbar}{2} \sum_{j \neq k} S_{jk} \Phi (r_{jk}) (z_k - z_j),
\]

where \((x_k, y_k)\) is the position of the \( k \)th vortex and \( z_k = x_k + iy_k = r_k e^{i \phi_k}, \quad r_k = |z_k|, \text{ and } r_{jk} = |z_k - z_j| \).

The topological charge of the \( k \)th vortex is \( S_k = \pm 1 \), with the positive (negative) sign referring to counter-clockwise (clockwise) circulation as viewed from the positive \( z \) axis. The constant parameter \( b \) modifies the interaction strength slightly from the homogeneous case in a harmonic trap; for experimentally relevant parameter values, it has been argued that to a good approximation it is given by \( b = 1.35 [16] \), while for the hard-wall potential it is \( b = 2 \).

The relevant velocities and coordinates for a vortex dipole are shown in Fig. 1c. Since the model is only valid for straight line vortices, we adopt the convention of referring to the location of a vortex line as the location of the vortex (particle).

3. Conserved quantities and integrability

The system of interest has a Hamiltonian structure. To see this, let us write the differential equations in Cartesian coordinates as

\[
\dot{x}_k = -i \Omega (r_k) y_k - \frac{b}{2} \sum_{j \neq k} S_{jk} \Phi (r_{jk}) (y_j - y_k),
\]

\[
\dot{y}_k = i \Omega (r_k) x_k + \frac{b}{2} \sum_{j \neq k} S_{jk} \Phi (r_{jk}) (x_j - x_k).
\]

For simplicity we work henceforth in dimensionless distance units with \( R = 1 \). Let us define the function

\[
H(z_1, \ldots, z_n) = -\frac{\Omega_0}{2} \sum_{k=1}^n \ln (1 - r_k^2)
\]

\[+ \frac{\Omega_R}{4} \sum_{k=1}^n \sum_{j \neq k} S_{jk} \ln (r_{jk}^2),
\]

where \( r_k = |z_k| = \sqrt{x_k^2 + y_k^2} \) and \( \Phi_R \equiv b \Phi (R) = \hbar b / m \) with \( R = 1 \).

Then, it can readily be found that

\[
S_k \dot{x}_k = -\frac{\partial H}{\partial y_k},
\]

\[
S_k \dot{y}_k = \frac{\partial H}{\partial x_k},
\]

for every \( k = 1, \ldots, n \), which means that \( H \) is a first conserved quantity, i.e., the first integral or Hamiltonian along the orbits of the system. Given initial positions \( z_k (0) \), then

\[
H(z_1(t), \ldots, z_n(t)) = E_0 \quad \forall t,
\]

for some suitable constant \( E_0 \).

It is directly verifiable that a second conserved quantity is

\[
V = \sum_{k=1}^n S_k r_k^2.
\]
which represents the angular momentum of the system; see, e.g., Ref. [29] for a discussion about conservation laws (in the absence of the precessional terms).

The existence of two conserved quantities guarantees integrability in the classical Liouville sense [30] for the case \( n = 2 \), whether the vortices are co- or counter-rotating. This implies that the energy level sets are compact and the phase space is foliated by invariant tori. On each of these, the motion is quasi-periodic with two frequencies. In the following, we consider other dynamical aspects of the \( n = 2 \) case for vortex dipoles with \( S_1 = 1 \) and \( S_2 = -1 \).

3.1. No collisions

Within the approximations of the present model, the two vortices never collide. To see this, we exploit the fact that the Hamiltonian is constant along orbits. Taking exponentials on the Hamiltonian, we have

\[
(1 - r_1^2)\dot{\Omega}_0 (1 - r_2^2)\dot{\Omega}_0 \frac{\phi_0}{r_{12}} = C^2 > 0 \quad \forall t,
\]

where \( C^2 = (1 - r_1^2)(1 - r_2^2)\dot{\Omega}_0 \dot{\Omega}_0 \frac{\phi_0}{r_{12}} \). Note that \( 0 < C^2 < 2\phi_0/2 \) because \( 0 \leq r_i(0)^2 < 1 \) (\( i = 1,2 \)) and \( 0 < r_{12}(0) < 2 \). A first consequence of Eq. (10) is

\[
r_{12}(t) > \frac{C^2}{\phi_0}\quad \forall t,
\]

that is, the vortices are separated by a computable minimal distance that depends on the initial position of the vortices.

It is worth reiterating that the model considers the dynamics of straight vortex lines only, such as those occurring in oblate BECs, and does not therefore preclude the possibility of collisions and possible reconnection phenomena when the vortex lines are tilted or bent.

3.2. No ejections

The vortices never reach the edge of the fluid, remaining confined instead within a computable inner circle. Assuming \( r_{12}(t) < 2 \) for all \( t \) (i.e., the distance between the two vortices cannot exceed twice the radius, \( R = 1 \), of the condensate), we have

\[
(1 - r_1^2)\dot{\Omega}_0 (1 - r_2^2)\dot{\Omega}_0 \frac{\phi_0}{r_{12}} > C^2 \quad \forall t,
\]

In consequence,\n
\[
r_{12}^2(t) < 1 - h,
\]

where \( h = (C^2 - \phi_0/2)^{1/\phi_0} < 1 \).

Again, it is worth noting that at finite temperature the dissipative presence of thermal atoms is expected to cause the vortices to leave the fluid. These effects are not considered in the present model.

4. The stationary equilibrium and its stability

We now prove the existence of a stationary equilibrium of the vortex pair dynamics and illustrate its stability.

4.1. Existence

\textbf{Lemma 1.} There is an equilibrium, unique up to rotations, given by

\[
(x_0^1, y_0^1) = \left(\sqrt{\frac{\Phi_R}{4\Omega_0 + \Phi_R}}, 0\right),
\]

\[
(x_0^2, y_0^2) = \left(-\sqrt{\frac{\Phi_R}{4\Omega_0 + \Phi_R}}, 0\right).
\]

\textbf{Proof.} Recall that \( n = 2 \) and \( S_1 = -S_2 = 1 \). The system (4) in complex notation is

\[
i\dot{z}_1 = -\Omega(r_1)z_1 + \frac{\phi_R}{2r_{12}^2} (z_1 - z_2),
\]

\[
i\dot{z}_2 = +\Omega(r_2)z_2 - \frac{\phi_R}{2r_{12}^2} (z_2 - z_1).
\]

Here \( z_1 = r_1 \exp(i\theta_1) \) and \( z_2 = r_2 \exp(i\theta_2) \) are, in general, time-dependent, but we look for equilibria, i.e., constant solutions. By direct substitution of the given solution above, one sees that it is indeed a constant solution. Let us prove that this is unique. Naturally, \( r_1 \) and \( \theta_1 \) denote polar coordinates (or equivalently an amplitude-phase decomposition). We can find that the evolution of such polar coordinates reads:

\[
\dot{\theta}_1 = \Omega(r_1) - \frac{\phi_R}{2r_{12}^2} \left[ 1 - \frac{r_2}{r_1} \cos(\theta_1 - \theta_2) \right],
\]

\[
\dot{\theta}_2 = -\Omega(r_2) + \frac{\phi_R}{2r_{12}^2} \left[ 1 - \frac{r_1}{r_2} \cos(\theta_1 - \theta_2) \right],
\]

\[
\dot{r}_1 = \frac{\phi_R r_2}{2r_{12}^2} \sin(\theta_1 - \theta_2),
\]

\[
\dot{r}_2 = \frac{\phi_R r_1}{2r_{12}^2} \sin(\theta_1 - \theta_2).
\]

Let us call \( \theta = \theta_1 - \theta_2 \). From the last equation, \( \sin \theta = 0 \). Then, \( \theta = 0 \) or \( \theta = \pi \). It is straightforward to show that the first option must be discarded. In particular, if \( \theta = 0 \), from the first equation

\[
0 = \Omega(r_1) - \frac{\phi_R}{2r_{12}^2} \left[ 1 - \frac{r_2}{r_1} \right],
\]

Since \( \Omega(r_1) > 0 \),

\[
1 - \frac{r_2}{r_1} = \frac{2r_{12}^2}{\phi_R} \Omega(r_1) > 0,
\]

and then \( r_1 > r_2 \). Arguing analogously with the second equation, one gets \( r_2 > r_1 \) and thus we reach a contradiction. In conclusion, it must be the case that \( \theta = \pi \). Now, we prove that \( r_1 = r_2 \). On the contrary, let us assume that \( r_1 > r_2 \) (the remaining case is analogous). Adding the two first equations

\[
\Omega(r_1) - \Omega(r_2) = \frac{\phi_R}{2r_{12}^2} \left[ \frac{r_2}{r_1} - \frac{r_1}{r_2} \right] < 0,
\]

which leads to a contradiction because \( \Omega(r) \) is strictly increasing.

In conclusion, \( \theta = \pi \) and we can find the exact value \( r_1 = r_2 = \sqrt{\frac{\phi_R}{4\Omega_0 + \Phi_R}} \) by solving the first equation of the system (15). \( \square \)

To emphasize the rotational invariance of our system, it is convenient to work with the variables \( (r_1, r_2, \theta) \). The (unique) equilibrium then reads

\[
(r_1^0, r_2^0,\theta_0) = \left(\sqrt{\frac{\Phi_R}{4\Omega_0 + \Phi_R}}, \sqrt{\frac{\Phi_R}{4\Omega_0 + \Phi_R}}, \pi\right).
\]

4.2. Stability

\textbf{Theorem 2.} The equilibrium \( (r_1^0, r_2^0,\theta_0) \) is stable (in the sense of Lyapunov).

\textbf{Proof.} In the coordinates \( (r_1, r_2, \theta) \), the system of Eqs. (14) reads
5. Guiding center equilibria and their stability

Finally, we prove the existence of a class of guiding center equilibria and illustrate their stability.

5.1. Existence

Consider two vortex positions \((x_1, y_1)\) and \((x_2, y_2)\), or in complex notation, \(z_1 = r_1 \exp(i\theta_1)\) and \(z_2 = r_2 \exp(i\theta_2)\), where all of the \(r\)'s and \(\theta\)'s are time-dependent. The system under study is

\[
i \dot{z}_1 = -\frac{\Omega_0}{1 - r_1^2} z_1 + \frac{\Phi_R}{2r_1^2} (z_1 - z_2),
\]

\[
i \dot{z}_2 = \frac{\Omega_0}{1 - r_2^2} z_2 - \frac{\Phi_R}{2r_2^2} (z_2 - z_1).
\]

We seek prograding guiding centers about which the vortices oscillate. For the special case of guiding centers equidistant from the center of the fluid, we expect the precession frequency \(\omega\) to vanish, reproducing the stationary equilibrium case above. Given a vortex positioned at one guiding center, and a (counter-circulating) anti-vortex at the other, we expect that each vortex will stay at its own guiding center; that is, if the guiding centers are themselves precessing, each vortex orbits the center of the condensate at the precession frequency of the guiding centers. From symmetry, we also expect the angular positions of the guiding centers to be \(\pi\) radians apart on a line that passes through the center of the condensate, i.e., on opposite sides of the center.

Therefore, we adopt a trial solution of the form

\[
z_1(t) = r_1 \exp(i\omega t),
\]

\[
z_2(t) = r_2 \exp(i\omega t + i\gamma t) = -r_2 \exp(i\omega t),
\]

where \(r_1\) and \(r_2\) are now constant, as is \(\omega\), the precession frequency of the guiding center. Note that in this case \(r_{12} = r_1 + r_2 = s\), the constant separation distance between the two guiding centers.

It is now convenient to introduce the notation:

\[
\alpha = \frac{1}{1 - r_1^2}, \quad \beta = \frac{1}{1 - r_2^2}, \quad \text{and} \quad \gamma = \frac{1}{2r_{12}} = \frac{1}{2s^2}.
\]

with \(\alpha\), \(\beta\), and \(\gamma\) all time-independent constants, by assumption.

Since the time dependence in \(z_1(t)\) and \(z_2(t)\) is now explicit, we take the derivatives directly:

\[
\dot{z}_1 = i\omega r_1 \exp(i\omega t) \quad \text{and} \quad \dot{z}_2 = -i\omega r_2 \exp(i\omega t),
\]

whereupon the differential equations become

\[
\alpha \dot{r}_1 = \alpha \Omega_0 r_1 - \gamma \Phi_R (r_1 + r_2),
\]

\[
\alpha \dot{r}_2 = -\beta \Omega_0 r_2 + \gamma \Phi_R (r_1 + r_2).
\]

Recalling \(s = r_1 + r_2 = (2\gamma)^{-1/2}\) as a final (as yet unused) constraint, we now have three equations and three unknowns \((r_1, r_2, \text{and} \, \omega)\): that is, upon choosing \(s\), the guiding center locations \(r_1\) and \(r_2\) can be identified in terms of \(s\), as well as the precession frequency of the guiding centers \(\omega\) — provided that there are solutions to this set of equations. Given the nature of the ensuing algebraic equations (see below), such solutions will generically exist. We derive the relevant equations below.

We start with the precession frequency \(\omega\). From the system of Eqs. (19) and (20), we find

\[
\omega = \frac{1}{2} \left[ \Omega_0 (\alpha - \beta) + \gamma \Phi_R \left( \frac{r_1}{r_2} - \frac{r_2}{r_1} \right) \right].
\]

Note that if \(r_2 = r_1\), then \(\alpha = \beta\) and \(\omega = 0\), recovering the expected stationary equilibrium.
Furthermore, from the same Eqs. (19) and (20) we immediately obtain:

$$\Omega_0(\alpha + \beta) - \gamma \Phi_R \left( \frac{1}{r_1^2} + \frac{1}{r_2^2} \right) = 0. \quad (22)$$

Substituting in for \(\alpha, \beta, \) and \(\gamma, \) in terms of \(r_1\) and \(r_2, \) and simplifying, one finds

$$\Omega_0 \left( \frac{1}{1 - r_1^2} + \frac{1}{1 - r_2^2} \right) - \frac{\Phi_R}{2 r_{12}} = 0. \quad (23)$$

Once the position of \(r_2\) is fixed, the location of the first vortex \(r = r_1\) can be found from the third order polynomial

$$\rho r^3 - \frac{\Phi_R}{r_2} r^2 - (\Omega_0 + \beta) r + \Phi_R \frac{r_2}{r_2} = 0. \quad (24)$$

An alternative possibility is to fix \(s\), then the location of the first vortex \(r = r_1\) can be found from the quartic algebraic equation

$$c_4 r^4 + c_3 r^3 + c_2 r^2 + c_1 r + c_0 = 0, \quad (25)$$

where the coefficients \(c_j (j = 0, 1, 2, 3)\) are given by:

$$c_0 = B (s^2 - 1),$$
$$c_1 = 2 s - s^3 - 2 s B,$$
$$c_2 = 3 s^2 - 2 - 2 (s^2 - 2),$$
$$c_3 = -4 s + 2 s B,$$
$$c_4 = 2 - B, \quad (26)$$

and \(B = \Phi_R / (2 \Omega_0).\)

5.2. Stability

In the following we prove the stability of the guiding center of the form

$$z_1(t) = r_1 \exp(i \omega t), \quad z_2(t) = -r_2 \exp(i \omega t), \quad (27)$$

obtained in the previous subsection. To this purpose, we pass to a co-rotating frame by making the change of variables \(z_1 = z_r \exp(-i \omega t)\) on the original system (14). Keeping the more convenient \(z_1\) notation for the state variables in a slight abuse of notation, the resulting system is

$$iz_1 = \omega z_1 - \Omega(r_1) z_1 + \frac{\Phi_R}{2 r_{12}} (z_1 - z_2),$$
$$iz_2 = \omega z_2 + \Omega(r_2) z_2 - \frac{\Phi_R}{2 r_{12}} (z_2 - z_1). \quad (28)$$

Note that a rotating solution like (27) of the original system (14) is equivalent to the statement that \((r_1, -r_2)\) is an equilibrium of the new system (28).

In Cartesian coordinates, the system (28) reads

$$\dot{x}_1 = \omega y_1 - \Omega(r_1) x_1 + \Phi_R \frac{y_1 - y_2}{2 r_{12}},$$
$$\dot{y}_1 = -\omega x_1 + \Omega(r_1) x_1 - \Phi_R \frac{x_1 - x_2}{2 r_{12}},$$
$$\dot{x}_2 = \omega y_2 + \Omega(r_2) y_2 - \Phi_R \frac{y_2 - y_1}{2 r_{12}},$$
$$\dot{y}_2 = -\omega x_2 - \Omega(r_2) x_2 + \Phi_R \frac{x_2 - x_1}{2 r_{12}}. \quad (29)$$

and passing to polar coordinates, we obtain

$$\dot{r}_1 = -\omega + \Omega(r_1) - \frac{\Phi_R}{2 r_{12}} \left[ 1 - \frac{r_2}{r_1} \cos(\theta_1 - \theta_2) \right],$$
$$\dot{r}_2 = -\omega - \Omega(r_2) + \frac{\Phi_R}{2 r_{12}} \left[ 1 - \frac{r_1}{r_2} \cos(\theta_1 - \theta_2) \right],$$
$$\dot{\theta}_1 = \frac{\Phi_R r_2}{2 r_{12}} \sin(\theta_1 - \theta_2),$$
$$\dot{\theta}_2 = \frac{\Phi_R r_1}{2 r_{12}} \sin(\theta_1 - \theta_2). \quad (30)$$

Of course, when \(\omega = 0\) we recover Eqs. (15).

Now the Hamiltonian is

$$H(r_1, r_2, \theta) = -\frac{\omega}{2} \left[ \frac{r_2^2}{r_1^2} - \frac{1}{2} \left( \Omega_0 \ln(1 - r_1^2) + \Omega_0 \ln(1 - r_2^2) \right) \right] + \frac{\Phi_R}{2} \left[ \ln(r_1^2 + r_2^2 - 2 r_1 r_2 \cos \theta) \right], \quad (31)$$

where again \(\theta = \theta_1 - \theta_2.\) But here the additional difficulty is the absence of a simple explicit expression for the solution.

Lemma 3. Any equilibrium of system (30) satisfies \(\theta = \pi.\)

Proof. From the last equation, \(\theta = \pi\) or \(\theta = 0.\) By contradiction, let us assume that \(\theta = 0.\) Then from the two first equations of system (30)

$$-\omega + \Omega(r_1) - \frac{\Phi_R}{2 r_{12}} \left[ 1 - \frac{r_2}{r_1} \right] = 0,$$
$$-\omega - \Omega(r_2) + \frac{\Phi_R}{2 r_{12}} \left[ 1 - \frac{r_1}{r_2} \right] = 0, \quad (32)$$

subtracting one from the other leads to

$$\Omega(r_1) + \Omega(r_2) = \frac{\Phi_R}{2 r_{12}} \left[ 2 - \frac{r_2}{r_1} - \frac{r_1}{r_2} \right] > 0,$$

then

$$2 - \frac{r_2}{r_1} - \frac{r_1}{r_2} > 0$$

and multiplying by \(r_1 r_2\) one gets \((-r_1 + r_2)^2 > 0,\) which is a contradiction. \(\square\)

Now it is ensured that any equilibrium should be of the form \((r_1, r_2, \pi).\) We can then compute the Hessian matrix of the Hamiltonian above, evaluated at the point \((r_1, r_2, \pi)\) and obtain

$$\begin{pmatrix}
\Omega(r_1) + \delta_1 + \delta_2 - \omega \\
\delta_1 \\
\delta_2 + \delta_1 + \omega \end{pmatrix} = 0,
$$

$$\begin{pmatrix}
\delta_1 \\
\delta_2 + \delta_1 + \omega \end{pmatrix} \begin{pmatrix}
0 \\
0 \delta_1 \delta_2 \end{pmatrix},$$

where \(\delta_1 \equiv \frac{2 \Omega_0 r_1}{(1 - r_1^2) r_1^2} > 0\) and \(\delta_2 \equiv \frac{\Phi_R}{2 r_1 r_2 (1-r_1^2)} > 0.\) Here it is difficult to see that the matrix is positive-definite, but, from Eqs. (32), the frequency \(\omega\) satisfies

$$\omega = \Omega(r_1) - \delta_1 \left( 1 + \frac{r_2}{r_1} \right) = -\Omega(r_2) + \delta_1 \left( 1 + \frac{r_2}{r_1} \right).$$

Inserting this information into the Hessian yields

$$\begin{pmatrix}
\delta_1 + \delta_2 (2 + \frac{r_2}{r_1}) & \delta_1 \\
\delta_2 & \delta_2 + \delta_1 (2 + \frac{r_2}{r_1}) \end{pmatrix},$$

and now one easily realizes that this matrix is positive-definite again by Sylvester’s criterion. Hence, once again the relevant
guiding-center equilibrium is a stable one, just as it is in the special case in which \( \omega = 0 \) and \( r_1 = r_2 \).

Rotating guiding center equilibria are relevant when the vortices are asymmetrically located with respect to a line through the condensate center. A representative example is given in Fig. 3: such behavior has been observed experimentally [21].

6. Conclusions

From the preceding calculations, we conclude that the vortex dipole system is an integrable one (this is true both in the co-rotating case, and in the counter-rotating one of principal interest herein). This implies that the energy level sets are therefore compact, and the phase space is foliated by invariant tori, on each of which the motion is quasi-periodic with two frequencies. In the context of the vortex dipoles, the first one of these frequencies is the precession of the guiding center equilibria which have been identified herein through the solution of relevant algebraic equations. The positive definite character of the Hessian of the linearization in the appropriate variables \( (r_1, r_2) \) and \( \theta = \theta_1 - \theta_2 \) guarantees stability of these equilibrium points. The second frequency is the oscillation frequency about the precessing equilibria.

Our analysis and conclusions offer a straightforward view of the dynamics of vortex dipoles when the vortex lines are straight, such as those arising in oblate, harmonically trapped Bose–Einstein condensates. Nevertheless, many interesting questions arise. On one hand, in the counter-rotating vortex case, it seems particularly interesting and relevant to extend the considerations above to the case of three- or more vortex states within the condensate and investigate the ensuing stationary [16] (and perhaps also guiding center) equilibria. On the other hand, another direction that naturally emerges concerns the examination of co-rotating vortices. In the latter case, we certainly expect the generalization of guiding center orbits, due to the common direction of rotation. Understanding the latter phenomenology in the general case of \( n \) vortices would arguably be interesting in its own right.

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