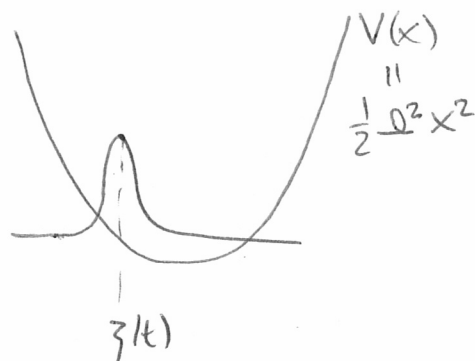


Describe next HW:

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(A) oscillating bright soliton inside a parabolic trap.



NLS: $i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = V(x)\psi$

• prove that Lagrangian is the same + $V(x)|\psi|^2$

• Ansatz: $\psi = \frac{\sqrt{N}}{\pi^{1/4}\sqrt{w}} e^{[-\frac{(x-z)^2}{w^2} + i\beta(x-z)^2 + i\phi]}$

Params: w, z, β, ϕ

• Obtain $\ddot{z} = -\frac{d}{dz} V_{\text{eff}}(z)$

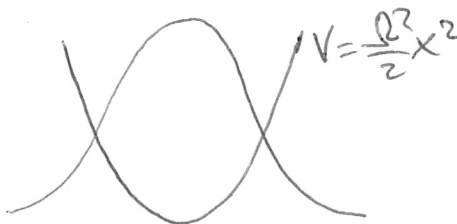
• compare PDE vs ODE.

(B) Nonlinear management

- * optical index of refraction can be spatially modulated
- * BEC nonlinearity (atom scattering) can be modulated:

NLS: $i\psi_t + \frac{1}{2}\psi_{xx} - U(t)|\psi|^2\psi = V(x)\psi$ (regulate BEC)

Start with steady state:
and use again Gaussian ansatz.



Q2: what happens if $U(t) = U_0(1 + \epsilon \sin(\alpha t))$
Q1: what happens if initial width/height are not @ steady state? $\rightarrow$ breathing periodic

Q3: Resonances: what if α is turned to ~~same~~ resonate with periodic breathing?

- (C) a) Use a such ansatz to recover NS soliton
b) perturb with loss
c) — with loss/gain.

Perturbation theory within Variational Approach

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[Sect: 7.4.2] 326-320

Take NLS:

$$i u_t + \frac{1}{2} u_{xx} \pm |u|^2 u = 0$$

+ : attractive
- : repulsive

Be careful, Scott's NLS is $i u_t + u_{xx} + 2|u|^2 u = 0$ so everything has to be renormalized

Perturb the equation:

$$i u_t + \frac{1}{2} u_{xx} \pm |u|^2 u = \underbrace{\varepsilon}_{\text{perturbation}} R(u, u_x, u_t, \dots, x, t) \quad |\varepsilon| \ll 1$$

Lagrangian for unperturbed:

$$L = \frac{i}{2} [u u_t^* - u^* u_t] + \frac{|u_x|^2}{2} \mp \frac{1}{2} |u|^4$$

$$-L = \frac{i}{2} [u^* u_t - u u_t^*] - \frac{|u_x|^2}{2} \pm \frac{1}{2} |u|^4$$

soliton solution (bright $\oplus$)

$$i u_t + \frac{1}{2} u_{xx} + |u|^2 u = 0$$

sol: a sech $a(x-ct+x_0) \exp[i(c x + \frac{a^2 c^2}{2c} t + \phi_0)]$

Ansatz: $u_A = a \operatorname{sech}(a(x-z)) \exp i [c(x-z) + i b]$

Lag: $L_A = \frac{i}{2} [\dots] = L(u_A)$

E-L eq:
$$\begin{cases} \ddot{a} = 0 \\ \dot{c} = 0 \\ \dot{z} = c \\ \dot{b} = a^2 c^2 \mp \frac{1}{2} a^2 \end{cases}$$

show VA-NLS. uNLS

HW

$$u = A e^{i\phi}$$

$$\frac{i}{2} (u u_t^* - u^* u_t) = \frac{i}{2} (A e^{i\phi} A e^{-i\phi} - A e^{-i\phi} A e^{i\phi}) = 0$$

$$|u_x|^2 = A^2 \phi_x^2$$

$$\frac{1}{2} u u_t^* = \frac{1}{2} A^2 \dot{\phi} = -\frac{1}{2} A^2 \phi_x^2$$

$$= \frac{1}{2} (A^2 \phi_x^2 + A^2 \phi_x^2)$$

so of ansatz = sech * modulation with chirp
→ one recovers the NLS soliton

Perturbed: Do Euler-Lag eq:

unperturbed: $\frac{d}{dt} \frac{\partial L_A}{\partial \dot{p}} = \frac{\partial L_A}{\partial p} \Rightarrow$ perturbed $\frac{\partial L_A}{\partial p} \frac{\partial L_A}{\partial t \partial p} = ?$

$$L \equiv L_A = L(u, u^*, u_t, u_t^*, u_x, u_x^*)$$

RHS: $\frac{\partial L_A}{\partial p} = \frac{\partial}{\partial p} \int_{-\infty}^{\infty} L_A dx = \int_{-\infty}^{\infty} \left[\frac{\partial L}{\partial u} \frac{\partial u}{\partial p} + \frac{\partial L}{\partial u_t} \frac{\partial u_t}{\partial p} + \frac{\partial L}{\partial u_x} \frac{\partial u_x}{\partial p} \right] + c.c. dx$

but $\int_{-\infty}^{\infty} \frac{\partial L}{\partial u_x} \frac{\partial u_x}{\partial p} dx = \int_{-\infty}^{\infty} u v' = u v - \int u' v$

$u = \frac{\partial L}{\partial u_x}$
 $v = \frac{\partial u}{\partial p}$

RHS = $\frac{\partial L_A}{\partial p} = \int_{-\infty}^{\infty} \left[\frac{\partial L}{\partial u} \frac{\partial u}{\partial p} + \frac{\partial L}{\partial u_t} \frac{\partial u_t}{\partial p} - \frac{\partial L}{\partial u_x} \frac{\partial u_x}{\partial p} \right] + c.c. dx$

now LHS: $LHS = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{p}} \right) = \int_{-\infty}^{\infty} \frac{\partial}{\partial t} \left[\frac{\partial L}{\partial u_t} \frac{\partial u}{\partial p} \right] + cc$

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now, $\frac{\partial u}{\partial p} = \frac{\frac{\partial u}{\partial t}}{\frac{\partial p}{\partial t}} = \frac{\partial u}{\partial p}$ if everything smooth.

since the only term with $\dot{p}$ is $u_t \Rightarrow \frac{\partial L}{\partial u} \frac{\partial u}{\partial p} + \frac{\partial L}{\partial u_t} \frac{\partial u}{\partial p}$

$$\begin{aligned} \Rightarrow LHS &= \int_{-\infty}^{\infty} \frac{\partial}{\partial t} \left[\frac{\partial L}{\partial u_t} \frac{\partial u}{\partial p} \right] + cc \\ &= \int_{-\infty}^{\infty} \left[\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial u_t} \right) \frac{\partial u}{\partial p} + \frac{\partial L}{\partial u_t} \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial p} \right) \right] + cc \\ &= \int_{-\infty}^{\infty} \left[\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial u_t} \right) \frac{\partial u}{\partial p} + \frac{\partial L}{\partial u_t} \frac{\partial u_t}{\partial p} \right] + cc \end{aligned}$$

$$\begin{aligned} \textcircled{1} &= \frac{i}{2} u_t^* + \frac{1}{2} 2u u^{*2} \\ &\quad - \frac{1}{2} u_{xx}^* + \frac{i}{2} u_t^* \\ &= i u_t^* - \frac{1}{2} u_{xx}^* + |u|^2 u^* \\ &= -NLS^* \end{aligned}$$

$\therefore RHS - LHS \Rightarrow \int_{-\infty}^{\infty} \frac{\partial u}{\partial p} \left[\frac{\partial L}{\partial u} - \frac{\partial \partial L}{\partial x \partial u} - \frac{\partial}{\partial t} \left(\frac{\partial L}{\partial u_t} \right) \right] + cc$

Remember that $\oint L dx dt = 0 \Leftrightarrow NLS$

Since $MS \Leftrightarrow \frac{\delta L}{\delta u^*} = 0 \Leftrightarrow \frac{\partial}{\partial t} \frac{\partial L}{\partial u_t^*} + \frac{\partial}{\partial x} \frac{\partial L}{\partial u_x^*} - \frac{\partial L}{\partial u^*} = 0$ [See Malomed Prog. Opt. 43 (2002) 71.]

$\therefore -NLS^* = 0 \Leftrightarrow -\frac{\partial}{\partial t} \frac{\partial L}{\partial u_t^*} + \frac{\partial}{\partial x} \frac{\partial L}{\partial u_x^*} + \frac{\partial L}{\partial u} = 0$

Now, add perturb: $\textcircled{1} = 0 \Rightarrow \textcircled{1} = -\epsilon R^*$

$\therefore RHS - LHS = -\epsilon \int_{-\infty}^{\infty} \frac{\partial u}{\partial p} R^* + cc = -2\epsilon \text{Re} \left[\int_{-\infty}^{\infty} R \frac{\partial u}{\partial p} \right]$

$\therefore \left[\frac{\partial L}{\partial p} - \frac{d}{dt} \frac{\partial L}{\partial \dot{p}} = \epsilon \int_{-\infty}^{\infty} \left(R^* \frac{\partial u}{\partial p} + R \frac{\partial u^*}{\partial p} \right) dx \right]$ Perturbed E-L eqns.

Ex1: add loss to NLS: $\left[\begin{array}{l} \text{Loss: suppose } |u| \ll 1 \text{ \& } u(x,t) = u(t) \\ \Rightarrow u_t = -\epsilon u \Rightarrow u(t) = u_0 e^{-\epsilon t} \end{array} \right]$

$i u_t + \frac{1}{2} u_{xx} \pm |u|^2 u + \epsilon i u = 0$, ie: $\epsilon R = -\epsilon i u$

Loss: dispersion relation: $u = A e^{i(kx - \omega t)}$

$\Rightarrow i A (-i \omega) + \frac{1}{2} A (ik)^2 \pm A^3 + \epsilon i A = 0$

$\rightarrow A \omega - \frac{1}{2} A k^2 \pm A^3 + \epsilon i A = 0$

$\Rightarrow \left[\omega = \frac{1}{2} k^2 \mp A^2 - i \epsilon \right] \rightarrow u = A e^{i k(x - (\frac{1}{2} k^2 \mp A^2)t) - \epsilon t}$

dispersion dissipation

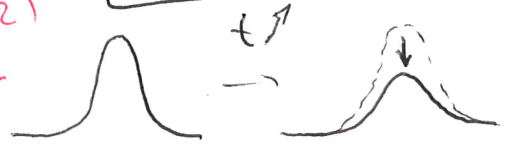
Q: what happens to soliton when we introduce some small dissipation? This is what happens in an optical fiber.

Perturbation: $R = -iU$

perturbed E-L eqs $\Rightarrow$

after neglecting ϵ^2 terms $\Rightarrow$

$$\begin{cases} \dot{a} = -\delta \epsilon a \\ \dot{c} = 0 \\ \dot{z} = c \\ \dot{b} = a^2 - c^2 = \alpha a^2 + \beta z^2 \end{cases}$$

$(1+U)$
 $(I \text{ think } \alpha = \frac{1}{2} = \beta \text{ (?)})$
 $\delta = +2$

 See Hogle VA-NLS.

Show NLS in NLS-spectral: $\text{mag} = \alpha |u|^2 - 0.01i$
 $\text{mag} = \alpha |u|^2 - 0.01i$

$a(t) = a_0 e^{-\delta \epsilon t} \therefore$ soliton keeps its shape but decays exponentially

$\delta = +2 \Rightarrow$ soliton decays twice as fast as a low amplitude sinusoidal wave.

Mathlab } try plane wave $\rightarrow e^{-\epsilon t}$
 try soliton $\rightarrow e^{-2\epsilon t}$

Ex2: add loss AND gain:

In an optical fiber one can add gain but the gain has to have a saturation (physical):

$$\epsilon R = \underbrace{-i\Gamma U}_{\text{damping loss}} + \underbrace{i \frac{g_0}{1+P/P_s} U}_{\text{focusing gain}} \quad P_s, g_0, \Gamma > 0$$

the gain is saturated for large wave amplitudes.

$$P = \int_{-\infty}^{\infty} |u|^2 dx$$

and P_s : saturation power level. I.e. when $P \sim P_s$ then saturation kicks in. Similar eq to since thus if for $(1+U+2|U|^2)u=0$ [Scott: 7.4.2]

Perturbed E-L: ---

$$\dot{a} = -2\Gamma a + \frac{2g_0}{1+2a^2/P_s} a \quad (1+U)$$

For $g_0=0$ we recover previous result, but for $g_0>0$ we indeed have a stationary solution when:

$$\Gamma = \frac{g_0}{1+2a^2/P_s} \Rightarrow a = a_{\infty} = \sqrt{\frac{(g_0-\Gamma)P_s}{2\Gamma}}$$

I.e. the soliton will adjust to $a \rightarrow a_{\infty}$

- $a(0) < a_{\infty} \Rightarrow \text{gain} > \text{loss} \Rightarrow a \uparrow$
- $a(0) > a_{\infty} \Rightarrow \text{gain} < \text{loss} \Rightarrow a \downarrow$
- $\therefore a = a_{\infty}$ is a stable equilibrium.

$0 < a < 1$
 $\Rightarrow \dot{a} \approx -2\Gamma a + 2g_0 a$
 $\approx 2a [g_0 - \Gamma]$
 If $g_0 > \Gamma \Rightarrow \dot{a} > 0$ for $a \ll 1$
 • $a \gg 1 \Rightarrow \dot{a} \approx -2\Gamma a < 0$
 • $a \gg 1 \Rightarrow \dot{a} < 0$


Soliton-soliton interactions using perturbation theory and the VA. [Based on Gerdjikov et al, PRE, 51 (1997) 6039]

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• NS: $i u_t + \frac{1}{2} u_{xx} + |u|^2 u = 0$

• suppose we have 2 solitons that are well separated

such that if

$$u_i = 2v_i \operatorname{sech} 2v_i [x - z_i(t)] e^{i \left[\frac{\mu_i}{v_i} [2v_i (x - z_i(t))] + \delta_i(t) \right]}$$

$$z_i(t) \equiv z_{i0} + 2\mu_i t$$

$$\delta_i(t) = 2(\mu_i^2 - v_i^2)t + \delta_{i0}$$

4 parameters $\vec{p}(t) = \begin{pmatrix} \mu_i(t) \\ v_i(t) \\ z_i(t) \\ \delta_i(t) \end{pmatrix}$

• suppose that $u = u_1 + u_2$ is a sol. to NLS:

$$i(u_{1t} + u_{2t}) + \frac{1}{2}(u_{1xx} + u_{2xx}) + (u_1 + u_2)^*(u_1 + u_2)(u_1 + u_2) = 0$$

$$\Rightarrow \text{---} + (u_1^* + u_2^*)(u_1^2 + 2u_1 u_2 + u_2^2) = 0$$

$$\Rightarrow i(u_{1t} + u_{2t}) + \frac{1}{2}(u_{1xx} + u_{2xx}) + \left[|u_1|^2 u_1 + |u_2|^2 u_2 + 2|u_1|^2 u_2 + u_1^* u_2^2 + 2|u_2|^2 u_1 + u_2^* u_1^2 \right] = 0$$

$$\Leftarrow i u_{it} + \frac{1}{2} u_{ixx} + |u_i|^2 u_i + 2|u_i|^2 u_j + u_i^2 u_j^* = 0 \quad \{i,j\} = \{1,2\} \text{ or } \{2,1\}$$

$$\Rightarrow i u_{it} + \frac{1}{2} u_{ixx} + |u_i|^2 u_i = - \left(2|u_i|^2 u_j + u_i^2 u_j^* \right)$$

perturbation induced on u_i by soliton j . $= iR$

$$\therefore R = \frac{1}{i} (2|u_i|^2 u_j + u_i^2 u_j^*) \leftarrow \text{small if solitons are separated}$$

• In Gerdjikov PRE 51 (1997) 6039 they consider 3 solitons and disregard higher order neighbors.



• Apply perturbation with VA and:

$$\frac{d}{dt} \vec{p}_k(t) = \frac{d}{dt} \begin{bmatrix} v_k \\ \mu_k \\ z_k \\ \delta_k \end{bmatrix} = f \left[\vec{p}_k, \vec{p}_{k-1}, \vec{p}_{k+1} \right] \quad \text{see [Gerdjikov p 6043 Eq 5 (20)-(23)] (35)-(38)}$$

• More simplifications $v_n \rightarrow v, \mu_n \rightarrow \mu$ in S & C 's

• $S, C \ll \mu$'s, v 's

$$\Rightarrow \text{Eq. (70)-(73)}$$

• change of variables:

$$\boxed{\frac{d^2 q_k}{dt^2} = e^{q_{k+1} - q_k} - e^{q_k - q_{k-1}}} \quad \text{Exp Toda chain}$$

with $q_k = q_k(v, z_k, S_k, s, \mu)$ see Eq (88)-(89)

• Very good agreement between numerics & approximation (even for large overlap). see Fig 3 x Fig 4

Ex: What is the dynamics of two nearby bright solitons? Dependence of phase?

Matlab

Perturbation theory for dark solitons

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Base on [Kivshor..., PRL 49 (1994) 1657]

- NLS: $i u_t + \frac{1}{2} u_{xx} - |u|^2 u = 0 \quad (2) \quad z \rightarrow t$
- plane wave $u = u_0 e^{i(kx - \beta t)} \quad (3)$
- $\Rightarrow$ dispersion relation: $\beta = \frac{1}{2} k^2 + u_0^2 \quad (7)$

- Integrals of motion for plane wave sol.

$$\left. \begin{array}{l} \text{Energy } E = \dots = \frac{P^2}{2L} + \frac{I^2}{2P} \\ \text{Momentum } I = \dots = k u_0^2 L = k P \\ \text{mass (power) } P = \dots = u_0^2 L \end{array} \right\} \int_{-\infty}^{\infty} \rightarrow \int_{-L}^L$$

$\frac{1}{2} k u_0^2 (2L)$

- Perturbation of plane wave:

$$u = (u_0 + v) e^{i(kx - \beta t + i\psi)} \quad \text{phase pert.}$$

$\uparrow$ amplitude pert

NLS

$$\Rightarrow i (u_0 + v) (-i\beta + i\dot{\psi}) e^{i(kx - \beta t + i\psi)} + \frac{1}{2} (u_0 + v) (ik + i\psi_{xx})^2 e^{i(kx - \beta t + i\psi)} - (u_0 + v)^3 e^{i(kx - \beta t + i\psi)} = 0$$

$$\Rightarrow \beta - \dot{\psi} + \frac{1}{2} (ik + i\psi_{xx})^2 - (u_0 + v)^2 = 0$$

$$\Rightarrow \beta - \dot{\psi} + \frac{1}{2} (-k^2 - 2k\psi_{xx} - \psi_{xx}^2) - (u_0^2 + 2u_0 v + v^2) = 0$$

$$|v| \ll 1 \quad \& \quad |\psi_{xx}| \ll 1$$

$$\Rightarrow \beta - \dot{\psi} + \frac{k^2}{2} - k\psi_{xx} - u_0^2 - 2u_0 v = 0$$

$$\Rightarrow \psi_t + k\psi_{xx} = \beta - \frac{k^2}{2} - u_0^2 - 2u_0 v$$

NLS

$$\Rightarrow i v_t (u_0 + v) e^{i(kx - \beta t + i\psi)} + i (u_0 + v) (-i\beta + i\dot{\psi}) e^{i(kx - \beta t + i\psi)} +$$

separate the 2 eqns. and suppose

$$v \propto e^{+i\Omega t - iqx} = e^{-i(qx - \Omega t)}$$

$$\psi \propto e^{+i\Omega t - iqx}$$

We obtain the dispersion relation for plane wave solutions:

$$(\Omega - kq)^2 = q^2 (u_0^2 + \frac{1}{4} q^2)$$

$\therefore$ if $\Omega > kq$ then $\Omega \in \mathbb{R} \Rightarrow$ no exponential growth!
 $\Rightarrow$ stable.

$$\Rightarrow \Omega = q(\sqrt{u_0^2 + \frac{1}{4} q^2} + k) \in \mathbb{R} \therefore \text{all perturbations are stable}$$

Similar to what we did before

step

- Now consider DS ^{with a carrier} ~~part of~~ plane wave (7) ~~above~~ 76

$$DS: u(x,t) = u_0 [A \tanh[u_0 A(x - vt)] + B] e^{-ikx - i\omega t + i\phi_0} \quad (12)$$

and $\beta = \frac{1}{2}k^2 + u_0^2$ and $u_0 B = v - k$, $A^2 + B^2 = 1$

DS: 3 params A, B, v but 2 eqs ^{↖ ↗} ie, only one indep. and the other 2 fixed by background ^{plane} wave.

- Note that Sol (12) has a plane wave asymptotes @ $x, t \rightarrow \pm\infty$
But since $\tanh$  $\rightarrow$  $\cdots$ 

phase shift $\approx \Delta\phi$

$\Rightarrow \Delta\phi = 2 [\tan^{-1}(\frac{B}{A}) - \frac{\pi}{2}] = -2 \tan^{-1}(\frac{A}{B})$

see: $x = -\infty$  $u_{-\infty} \sim (A + iB)e^{+i \tan^{-1} \frac{B}{A}}$
 $u_{+\infty} \sim (A + iB)e^{-i \tan^{-1} \frac{B}{A}}$ $\Delta\phi =$

- let us now use integrals of motion

$\rightarrow$ problem: integrals are ∞

$\rightarrow$ let us remove the background since we are interested in DS only.

$\rightarrow$ commonly known as regularizing the integral (also renormalizing).

- let us do the regularization for $k=0$, ie: flat background:

$$\beta = u_0^2, \quad u_0 B = v, \quad A^2 + B^2 = 1, \quad \boxed{C = u_0}$$

also for $k=0$ disp. relation for background wave:

✓ Power: $\boxed{P_s = \int_{-\infty}^{\infty} (u^2 - u_0^2) dx}$ (since $P = u_0^2 L$)

$$P_s = 2u_0 A$$

because $k=k(x)$

- Momentum: one has to subtract a term related with phase shift. [^]

$\rightarrow$ since $I = \frac{1}{2}k u_0^2 x$ $\leftarrow$ contribution of background.

$\rightarrow$ @ $x = \pm\infty$ this is zero, but close to DS is not, so

one has to remove $\frac{1}{2} \int u_0^2 k = \frac{1}{2} u_0^2 \int k(x) dx$

and $\int_{-\infty}^{\infty} k(x) dx = \Delta\phi = -2 \tan^{-1}(\frac{A}{B})$

Wave #

skip $\left[\therefore \left[I_s = \frac{i}{2} \int_{-\infty}^{\infty} (u u_x^* - u^* u_x) dx - u_0^2 \Delta \phi \right]_{k=0} = I - u_0^2 \Delta \phi \right.$

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$= -2V \sqrt{c^2 - v^2} + 2c^2 \tanh^{-1} \left(\frac{\sqrt{c^2 - v^2}}{v} \right)$

where $(c \equiv u_0)$

Energy: similarly:

$$\left[E_s = \int_{-\infty}^{\infty} \left(\frac{1}{2} |u|^2 + \frac{1}{2} (|u|^2 - u_0^2)^2 \right) dx \right]_{k=0}$$

$$= \frac{4}{3} (c^2 - v^2)^{3/2}$$

Now we are ready to use this conservation laws that remove background and follow the DS:

III. A Constant background

- perturbed NLS: $i u_t + \frac{1}{2} u u_{xx} - |u|^2 u = \epsilon P(u)$
- assume perturbation does not change background @ $x = \pm \infty$
i.e.: $P(u(x = \pm \infty)) = 0$
- constant background ($k=0$) $\Rightarrow$ plane wave $u = u_0 e^{-i u_0^2 t}$
($\beta = \frac{1}{2} k^2 + u_0^2$)

- let us then factor out the constant background from the solution we are interested in:

$$u(x,t) = u_0 e^{-i u_0^2 t} v(x,t)$$

then follow $v(x,t)$:

$\rightarrow u(x,t)$ in NLS $\Rightarrow i v_\tau + \frac{1}{2} v v_{\tau\tau} - (|v|^2 - 1) v = \epsilon \tilde{P}(v)$ (23)

where $\tau = u_0^2 t$ & $\xi = u_0 x$

- Analyze how DS forms change due to presence of $\epsilon \tilde{P}(v)$
- Ansatz for DS in eq for $\epsilon=0$

$$\left[v(\xi, \tau) = \frac{\eta}{\cosh \eta(\xi - \Omega \tau)} - i \frac{\Omega}{\cosh \eta(\xi - \Omega \tau)} \right]$$

$\eta = \cos \phi, \Omega = \sin \phi = \text{vel.}$

a single parameter $\phi(\tau)$ (since we already assume (since we assume a const. background $\neq 1$ because u_0 is factored out))
it is going @ speed c due to the background level

- Applying pert. machinery:

$$\left[\frac{d\phi}{d\tau} = \frac{\epsilon}{2 \cos^2 \phi \sinh} \operatorname{Re} \left[\int_{-\infty}^{\infty} \left(\tilde{P}(v) \frac{\partial v^*}{\partial \tau} \right) d\xi \right] \right] \quad (24)$$

Application : ~~loss~~ gain with saturation

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NLS : $i u_t + \frac{1}{2} u_{xx} - |u|^2 u = i\alpha u - iK |u|^2 u$

linear gain ~~loss~~ nonlinear absorption

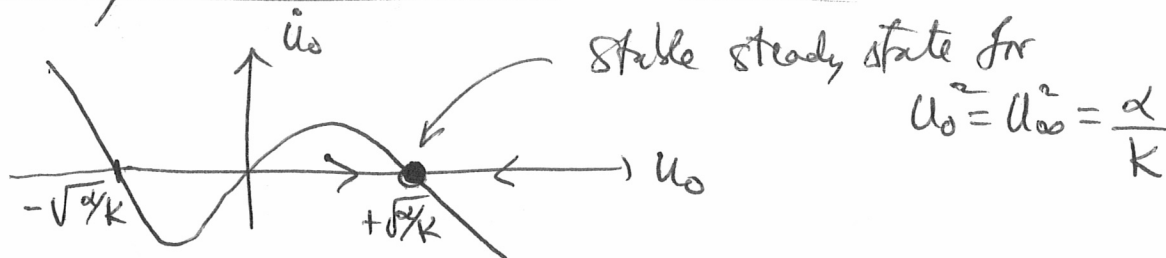
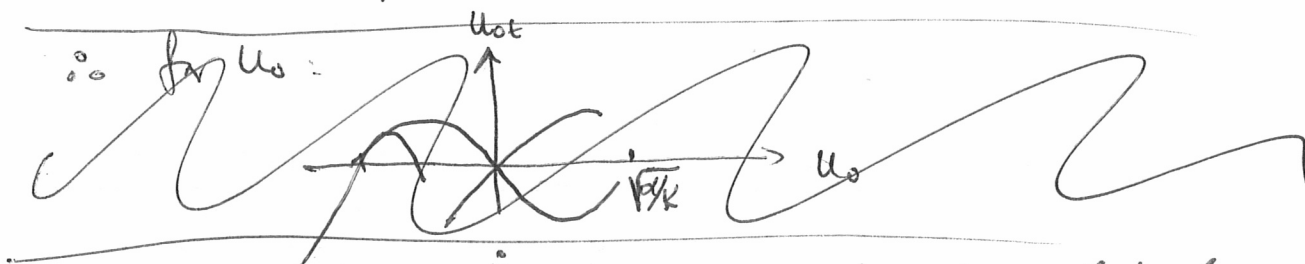
dispersion relation : $u = (u_0(t)) e^{i(kx - \beta t)}$ [α, K small]

$i(u_{0t} e^{i(kx - \beta t)} + u_0(-i\beta) e^{i(kx - \beta t)}) + \frac{1}{2} u_0 (ik)^2 e^{i(kx - \beta t)} - u_0^3(t) e^{i(kx - \beta t)} = i\alpha u_0 e^{i(kx - \beta t)} - iK u_0^3 e^{i(kx - \beta t)}$

$\Rightarrow i(\frac{u_{0t}}{u_0} + (-i\beta)) + \frac{1}{2} u_0 k^2 - u_0^2 = i\alpha - iK u_0^2$

$\Rightarrow i \frac{u_{0t}}{u_0} + \beta - \frac{1}{2} u_0 k^2 - u_0^2 = i\alpha - iK u_0^2$

$\Rightarrow \begin{cases} u_{0t} = \alpha u_0 - K u_0^3 = u_0 (\alpha - K u_0^2) \\ \beta = \frac{1}{2} u_0 k^2 + u_0^2 \end{cases}$



If $u_0 < u_{\infty} \rightarrow$ gain } interplay between linear and
 $u_0 > u_{\infty} \rightarrow$ loss } the nonlinear gain.

• let us study a DS on this stable background.

$\rightarrow$ ansatz $u(x,t) = u_{\infty} v(x,t) e^{-i u_{\infty}^2 t}$ (*)

NLS $i v_t + \frac{1}{2} v_{xx} - (|v|^2 - 1) v = -iK (|v|^2 - 1) v$ } α no longer here because normalization $y = \frac{t\alpha}{K}$

$y \equiv \frac{t\alpha}{K}, \quad \tau \equiv x \sqrt{\frac{\alpha}{K}}$

• Note that $v=1$ we recover stable $u=u_{\infty}$ background, but as soon as $|v| \neq 1$ then we have a perturbation ~~amplitude~~ of size K

① in (291) $\Rightarrow P(v) = -iK(|v|^2 - 1)v$, $v = \eta \tanh \eta(\tau - \tau_0) - i\Omega$, $\eta = \cos \phi$, $\Omega = \sin \phi$, $y = \frac{t\alpha}{K}$

$\Rightarrow \frac{d\phi}{dy} = \frac{1}{2\cos \phi \sin \phi} \operatorname{Re} \left[\int_{-\infty}^{\infty} -iK(|v|^2 - 1)v \frac{\partial v^*}{\partial \tau} d\tau \right] = \frac{1}{2\cos \phi} \operatorname{Re} \left[\int_{-\infty}^{\infty} -iK[(\eta^2 \tau^2 + \Omega^2) - 1] \frac{\partial}{\partial y} [\eta \tau + i\Omega] d\tau \right] = \dots$

Ans on (29): $\frac{d\phi}{dt} = \frac{\alpha}{3} \sin(2\phi)$ (back to t [$y = \frac{t\alpha}{K}$])

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$\Rightarrow \phi(t) = \tan^{-1} [\tan \phi_0 e^{\frac{2}{3}\alpha t}]$ (independent on K)

$\therefore \bullet \phi(0) = 0 \rightarrow \phi(t) = 0 \Rightarrow$ stationary solution

$U = \eta \tanh \eta (z - \Omega t) - i\Omega$

$\eta = \cos \phi = 1, \Omega = \sin \phi = 0$
↑ vel.

$\bullet \phi(0) \neq 0 \Rightarrow \phi(\infty) = \tan^{-1}[\infty] = \frac{\pi}{2} \operatorname{sgn}(\phi_0)$

$\Rightarrow \eta \rightarrow 0, \Omega = \pm 1$ $\therefore$ infinite width zero height.

$\rightarrow$ it: decay of DS.

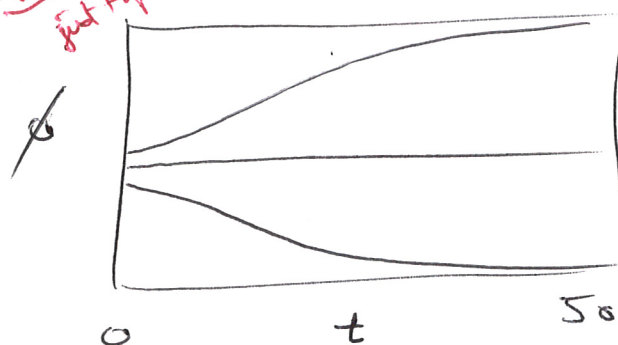
$\bullet$ Note that velocity of DS $= \Omega = \sin \phi$.

So an initial steady DS $\Omega = 0$ ($\phi = 0$)

will be unstable since any change in ϕ will

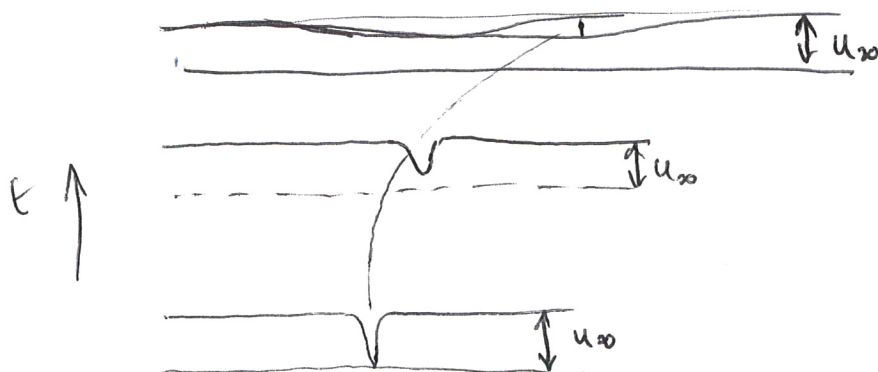
make $\phi \rightarrow \pm \pi/2$ and destroy soliton.
just forget.

Show Matlab
 spectral
 IL = (2 DS @ $4/2 \pm 4/2$) $\times \exp(0.001 \times t)$
- u.s. (logical)



($\alpha = 0.1$)

$\bullet$ Dynamics $\rightarrow$ if $\phi \neq 0 \Rightarrow$ soliton accelerates until it gets infinitely spread.



3D → 2D GPE Reduction

Let us start with fully dimensional 3D GPE eq:

$$i\hbar \psi_t = \left[-\frac{\hbar^2}{2m} \nabla^2 + \frac{m}{2} \underbrace{(\omega_x^2 x^2 + \omega_y^2 y^2 + \omega_z^2 z^2)}_{V(x,y,z)} + g |\psi|^2 \right] \psi \quad (1)$$

We suppose a "pancake" trap where $\omega_z \gg \omega_x \approx \omega_y \equiv \omega_r$

$$\Rightarrow V(x,y,z) \rightarrow \frac{m}{2} (\omega_r^2 r^2 + \omega_z^2 z^2)$$

In this quasi-2D scenario the wave function will not be able to be excited in the z -direction $\Rightarrow$ in the z -direction the system will be in its "ground state".

[ground state of a harmonic trap $\rightarrow$ quantum harmonic oscillator
 $\rightarrow$ Gaussian]

- So let us do:
- separation of variables: $\psi_{3D} = \psi_{2D} \cdot \phi(z) \cdot f(t)$
 - method of averaging ~~the~~ over z -direction

3D → 2D: $\psi_{3D} = \psi_{2D} \phi(z) e^{-i\frac{\gamma}{\hbar} t}$ (separation of variables)

$$\Rightarrow \phi_0 \left[i\hbar \frac{\partial}{\partial t} \psi_{2D} e^{-i\frac{\gamma}{\hbar} t} \right] = \int_z \left(-\frac{\hbar^2}{2m} \nabla_z^2 \psi \right) \phi_0 e^{-i\frac{\gamma}{\hbar} t} + \int_z \left[\frac{\hbar^2}{2m} \phi_0'' e^{-i\frac{\gamma}{\hbar} t} + [V + g \phi_0^2 |\psi_{2D}|^2] \phi_0 \psi_{2D} e^{-i\frac{\gamma}{\hbar} t} \right]$$

$$\Rightarrow i\hbar \frac{\partial}{\partial t} [\psi_{2D} e^{-i\frac{\gamma}{\hbar} t}] = -\frac{\hbar^2}{2m} \nabla_z^2 \psi_{2D} e^{-i\frac{\gamma}{\hbar} t} - \frac{\hbar^2}{2m} \frac{\phi_0''}{\phi_0} e^{-i\frac{\gamma}{\hbar} t} \psi_{2D} + [V + g \phi_0^2 |\psi_{2D}|^2] \psi_{2D} e^{-i\frac{\gamma}{\hbar} t}$$

$$\Rightarrow i\hbar \left(\frac{\partial}{\partial t} \psi_{2D} \right) e^{-i\frac{\gamma}{\hbar} t} + i\hbar \psi_{2D} \left(-i\frac{\gamma}{\hbar} \right) e^{-i\frac{\gamma}{\hbar} t} = -\frac{\hbar^2}{2m} \nabla_z^2 \psi_{2D} e^{-i\frac{\gamma}{\hbar} t} - \frac{\hbar^2}{2m} \frac{\phi_0''}{\phi_0} e^{-i\frac{\gamma}{\hbar} t} \psi_{2D} + [V + g \phi_0^2 |\psi_{2D}|^2] \psi_{2D} e^{-i\frac{\gamma}{\hbar} t}$$

$$\div \psi_{2D} \Rightarrow i\hbar \frac{\partial \psi_{2D}}{\partial t} + \frac{\hbar^2 \gamma}{2m} \psi_{2D} = -\frac{\hbar^2}{2m} \frac{\nabla_z^2 \psi_{2D}}{\psi_{2D}} - \frac{\hbar^2}{2m} \frac{\phi_0''}{\phi_0} + [V + g \phi_0^2 |\psi_{2D}|^2]$$

$$i\hbar \frac{\partial \psi_{2D}}{\partial t} + \frac{\hbar^2 \gamma}{2m} \frac{\psi_{2D}^2}{\psi_{2D}} - \frac{1}{2} m (\omega_x^2 + \omega_y^2) \frac{\psi_{2D}^2}{\psi_{2D}} - g \phi_0^2 |\psi_{2D}|^2 = -\frac{\hbar^2 \gamma}{2m} - \frac{\hbar^2}{2m} \frac{\phi_0''}{\phi_0} + \frac{1}{2} m \omega_z^2 z^2$$

$$\Rightarrow \begin{cases} \frac{\hbar^2}{2m} \phi_0'' - \frac{1}{2} m \omega_z^2 z^2 \phi_0 + \frac{\hbar}{4} \gamma \phi_0 = 0 \Rightarrow -\frac{\hbar^2}{2m} \phi_0'' = \left[-\frac{1}{2} m \omega_z^2 z^2 + \gamma \right] \phi_0 \\ i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \psi + \left[\frac{1}{2} V_2 + g_3 \phi_0^2 + \hbar^2 \right] \psi \end{cases}$$

$$\boxed{\phi_0} \quad \phi_0(z) = A e^{-\frac{z^2}{2\beta^2}} \Rightarrow \cancel{\frac{\hbar^2}{2m} A \phi_0''} \quad \phi_0' = A \left(-\frac{z}{\beta^2} \right) e^{-\frac{z^2}{2\beta^2}}$$

$$\Rightarrow \phi_0'' = A \left[-\frac{1}{\beta^2} e - \frac{z}{\beta^2} \left(-\frac{z}{\beta^2} \right) e \right]$$

$$\therefore \frac{\hbar^2}{2m} \left[-\frac{1}{\beta^2} + \frac{z^2}{\beta^4} \right] - \frac{m}{2} \omega_z^2 z^2 + \frac{\hbar}{4} \gamma = 0$$

$$\Rightarrow \left[-\frac{\hbar^2}{2m\beta^2} + \frac{\hbar}{4} \gamma \right] + \left[\frac{\hbar^2}{2m\beta^4} - \frac{m}{2} \omega_z^2 \right] z^2 = 0$$

$$\Rightarrow \gamma = \frac{\hbar^2}{2m\beta^2}, \quad m\omega_z^2 = \frac{\hbar^2}{m\beta^4}, \quad \gamma = \frac{\hbar^2}{2m\beta^2} \cdot \frac{1}{\beta^2} = \frac{\hbar^2}{2m\alpha_z^2} = \frac{\hbar^2}{2m} \frac{m\omega_z^2}{\hbar}$$

$\gamma = \frac{\hbar \omega_z}{2}$

$$\Rightarrow \left[\beta^2 = \frac{\hbar}{m\omega_z} = a_z^2 \right] \quad \left[a_z^2 \equiv \frac{\hbar}{m\omega_z} \right]$$

$$\therefore \phi_0(z) = A e^{-\frac{z^2}{2a_z^2}}$$

$$\int_{-\infty}^{\infty} e^{-\frac{z^2}{2a_z^2}} dz = \sqrt{2\pi} a$$

$$\therefore \text{If } \underbrace{\int |\phi|^2}_{\text{normalize}} = 1 \Rightarrow A^2 \int e^{-\frac{z^2}{a_z^2}} = 1 \Rightarrow A^2 a_z \sqrt{\pi} = 1$$

$$\Rightarrow \boxed{A = \pi^{-1/4} a_z^{-1/2}}$$

$$\therefore \boxed{\phi_0(z) = \pi^{-1/4} a_z^{-1/2} e^{-\frac{z^2}{2a_z^2}}} \Rightarrow \phi_0'' = \pi^{-1/4} a_z^{-1/2} \left[-\frac{1}{a_z^2} + \frac{z^2}{a_z^4} \right] e$$

$$= \left[-\frac{1}{a_z^2} + \frac{z^2}{a_z^4} \right] \phi_0$$

$$\boxed{\psi_2} \quad i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \psi + \frac{1}{2} V_2 +$$

GPE : $i\hbar \psi_t = \left[-\frac{\hbar^2}{2m} \nabla^2 + \frac{1}{2} V_3 + g_3 |\psi|^2 \right] \psi$

$\psi_3 = \psi_2 \phi_0 e^{-i\frac{\omega_2 t}{\hbar}}$

Average over z $\left[\int GPE \cdot \phi_0^* dz \right] \Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} \phi_0 + \cancel{\delta \psi_2 \phi_0} = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 \phi_0 - \frac{\hbar^2}{2m} \frac{\phi_0''}{\phi_0} \psi_2 + [V + g \psi_2^2 / \psi_2^2] \psi_2 \phi_0$

$\Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} + \delta \psi_2 = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 - \frac{\hbar^2}{2m} \left[-\frac{1}{a_z^2} + \frac{z^2}{a_z^4} \right] \psi_2 + [V + g$

$\times \phi_0^* (= \times \phi_0)$ $\Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} \phi_0^2 + \delta \psi_2 \phi_0^2 = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 \phi_0^2 - \frac{\hbar^2}{2m} \phi_0'' \phi_0 \psi_2 [\psi_2 \phi_0^2]$

$\int dz \Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} \phi_0^2 + \delta \psi_2 \phi_0^2 = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 \phi_0^2 - \frac{\hbar^2}{2m} \phi_0'' \phi_0 \psi_2 [\psi_2 \phi_0^2]$

$\int dz \Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} + \delta \psi_2 = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 - \frac{1}{2} m \omega_z^2 z^2 \psi_2 + \delta \psi_2 + [V_1 + V_2] \psi_2 + g \int \psi_2^4$

$[\psi_2^2 = 1]$

$\Rightarrow i\hbar \frac{\partial \psi_2}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 + V_2 \psi_2 + g_3 \int \phi_0^4 |\psi_2|^2 \psi_2$

$\therefore g_2 \equiv g_3 \int \phi_0^4 = g_3 \frac{1}{2} \sqrt{\frac{2}{\pi}} \frac{1}{a_z} = g_3 \frac{1}{\sqrt{2\pi} a_z}$

$\therefore \boxed{g_2 = g_3 \frac{1}{\sqrt{2\pi} a_z}}$

$\Rightarrow \boxed{i\hbar \frac{\partial \psi_2}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \psi_2 + \left[\frac{1}{2} m (\omega_x^2 x^2 + \omega_y^2 y^2) + g_2 |\psi_2|^2 \right] \psi_2} \quad (2)$

$\psi_3 = \psi_2 \phi_0 e^{-i\frac{\omega_2 t}{\hbar}}, \quad \phi_0(z) = \pi^{-1/4} a_z^{-1/2} e^{-\frac{z^2}{2a_z^2}},$

$a_z^2 \equiv \frac{\hbar}{m\omega_z}, \quad \delta \equiv \frac{\hbar\omega_z}{2} \Rightarrow \frac{\delta}{\hbar} = \frac{\omega_z}{2} \Rightarrow [] = 1/4 \checkmark$

$g_2 \equiv g_3 \frac{1}{\sqrt{2\pi} a_z}, \quad g_3 = \frac{4\pi\hbar^2 a}{m} \Rightarrow \sqrt{2\pi} a_z g_2 = \frac{4\pi\hbar^2 a}{m}$

Adm:

$$\omega_r \equiv \omega_x = \omega_y$$

$$\tau = \omega_z t, \quad R = r/\lambda, \quad \zeta^2 = \frac{\hbar}{m\omega_z}$$

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$$\xrightarrow{(2)} \\ t \rightarrow \tau, R \rightarrow R$$

$$i\hbar\omega_z \frac{\partial \Psi}{\partial \tau} = -\frac{\hbar^2}{2m} \frac{m\omega_z}{\hbar} \nabla_R^2 \Psi + \left[\frac{1}{2} m\omega_r^2 \frac{\hbar^2}{m\omega_z} R^2 + g_2 |\Psi|^2 \right] \Psi$$

$$\div \hbar\omega_z \quad i\Psi_\tau = -\frac{1}{2} \nabla_R^2 \Psi + \left[\frac{1}{2} \Omega^2 R^2 + \frac{g_2}{\hbar\omega_z} |\Psi|^2 \right] \Psi$$

$$\boxed{\Omega \equiv \frac{\omega_r}{\omega_z}}$$

$$\bar{\Psi} = (4\pi\zeta^2)^{1/2} \Psi = \left(\frac{\hbar}{m\omega_z} \frac{g_3 \hbar}{4\pi\hbar} \right)^{1/2} \Psi = \left(\frac{g_3}{\omega_z} \right)^{1/2} \Psi$$

$$\Rightarrow i\bar{\Psi}_\tau = -\frac{1}{2} \nabla_R^2 \bar{\Psi} + \left[\frac{1}{2} \Omega^2 R^2 + \frac{g_3}{\sqrt{2\pi}a_z} \frac{1}{\hbar\omega_z} \frac{\omega_z}{g_3} |\bar{\Psi}|^2 \right] \bar{\Psi}$$

$$\text{Adm } \Psi: \quad b\bar{\Psi} = \Psi \Rightarrow i\bar{\Psi}_\tau = -\frac{1}{2} \nabla^2 \bar{\Psi} + \left[\frac{1}{2} \Omega^2 R^2 + \frac{g_2 b^2}{\hbar\omega_z} |\bar{\Psi}|^2 \right] \bar{\Psi}$$

$$\therefore b^2 = \frac{\hbar\omega_z}{g_2}$$

$$\Rightarrow \boxed{\Psi_2 = \sqrt{\frac{\hbar\omega_z}{g_2}} \bar{\Psi}_2}$$

$$\left[\begin{aligned} b^2 &= \frac{\hbar\omega_z}{g_3} = \frac{\hbar\omega_z m}{4\pi\hbar^2 a} = \frac{m\omega_z}{4\pi a \hbar} \\ 4\pi\zeta^2 a &= 4\pi \frac{\hbar}{m\omega_z} a \end{aligned} \right]$$

$$\begin{aligned} &= \boxed{\begin{aligned} i\frac{\partial \bar{\Psi}}{\partial \tau} &= -\frac{1}{2} \nabla^2 \bar{\Psi} + \left[\frac{1}{2} \Omega^2 R^2 + |\bar{\Psi}|^2 \right] \bar{\Psi} \\ \Psi_3 &= \Psi_2 \phi, \quad \phi(z) = \pi^{-1/4} a_z^{-1/2} e^{-\frac{z^2}{2a_z^2}} \\ \zeta^2 &= a_z^2 \equiv \frac{\hbar}{m\omega_z}, \quad \delta \equiv \frac{\hbar\omega_z}{2}, \quad \Omega = \omega_r/\omega_z \\ \Psi_2 &= \sqrt{\frac{\hbar\omega_z}{g_2}} \bar{\Psi}_2, \quad g_2 \equiv g_3 \frac{1}{\sqrt{2\pi}a_z}, \quad g_3 = \frac{4\pi\hbar^2 a}{m} \\ \tau &= \omega_z t, \quad R = r/\lambda, \quad \zeta^2 = \frac{\hbar}{m\omega_z} = a_z^2 \end{aligned}} \end{aligned}$$

Adimensionalized

+

reduced 3D-2D

GPE.

Ring dark solitons

[Theodanis + Frant. + PGK + BAM + Kuvshov, 90 PRL (2003) 120403]

- Take a BEC in 3D:

$$i\hbar u_t + \frac{1}{2}\nabla^2 u + |u|^2 u = V(x,y,z) u$$

- Use trapping potential:

$$V(x,y,z) = \frac{1}{2} (\Omega_x^2 x^2 + \Omega_y^2 y^2 + \Omega_z^2 z^2)$$

such that $\Omega_z \gg \Omega_x = \Omega_y \equiv \Omega$

$\Rightarrow$ 3D BEC $\rightarrow$ 2D "pancake" BEC. [See my chap contribution to BEC book] sec. 4.2
(Ω need to be rescaled when 3D $\rightarrow$ 2D)

$u = u(x,y)$, Repulsive:

$$i\hbar u_t + \frac{1}{2}(\hbar^2 u_{xx} + \hbar^2 u_{yy}) - |u|^2 u = \frac{1}{2} \Omega^2 r^2 u \quad (r^2 = x^2 + y^2)$$

- use polar coord. $\nabla^2 \rightarrow \nabla_r^2 + \frac{1}{r} \partial_r$

and consider $u(x,y,t) = u(r,\theta,t) = u(r,t)$ only:

$$i\hbar u_t + \frac{\hbar^2}{2} \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} - |u|^2 u = \frac{\Omega^2}{2} r^2 u \quad \text{1D problem in radial direction.}$$

- Thomas-Fermi approx [See my chap contribution to BEC book. Sec 5.1]

repulsive BEC: $i\hbar u_t + \frac{1}{2}\nabla^2 u + |u|^2 u = \frac{\Omega^2}{2} r^2 u$

+ $\iiint |u|^2 dx dy dz \gg 1 \rightarrow$ slow spatial variation compared to potential
 $\Rightarrow \nabla^2 u \ll V u$.

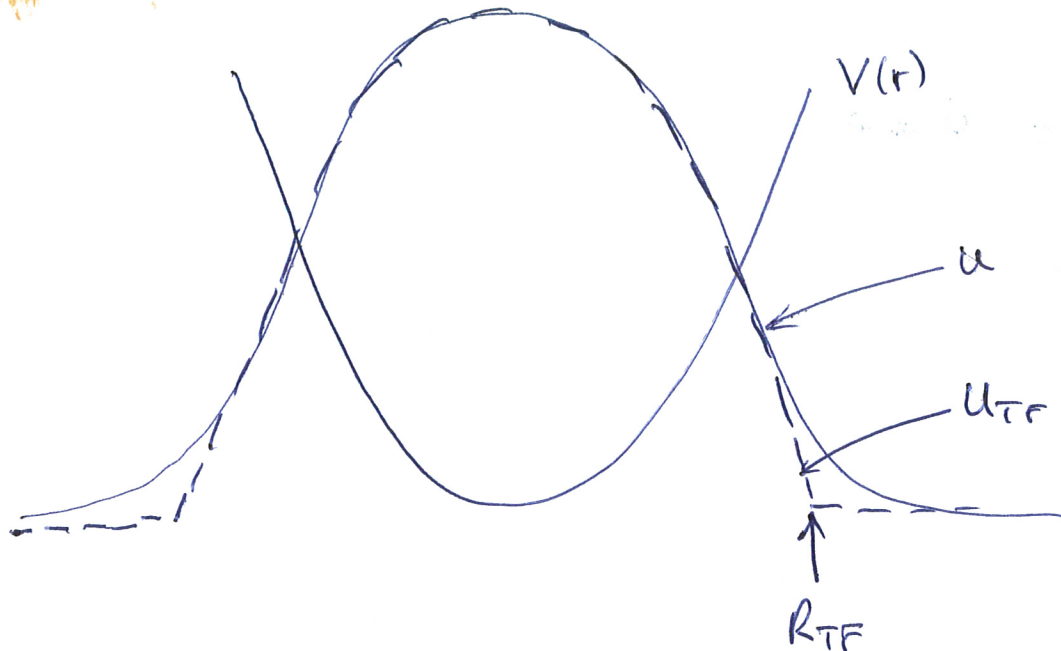
$\Rightarrow$ steady state: $u = u_{TF} e^{-i\mu t}$,

$$\Rightarrow \mu u_{TF} - \frac{\hbar^2}{2} \nabla^2 u_{TF} \approx V(r) u_{TF}$$

$$\Rightarrow \boxed{u_{TF} \approx \sqrt{\mu - V(r)} \quad \text{for } r > R_{TF}}$$

← Thomas-Fermi approx
← Thomas-Fermi radius

• R_{TF} : $V(R_{TF}) = \mu \Rightarrow \frac{1}{2} \Omega^2 R_{TF}^2 = \mu$
 $\Rightarrow \boxed{R_{TF} = \frac{\sqrt{2\mu}}{\Omega}}$



- More approx : number of atoms N :

$$N = \iiint |\psi|^2 dx dy dz \approx \iiint_{|r| < R_{TF}} \mu - V dr$$

$\approx 2\pi R_{TF}^2 \mu$

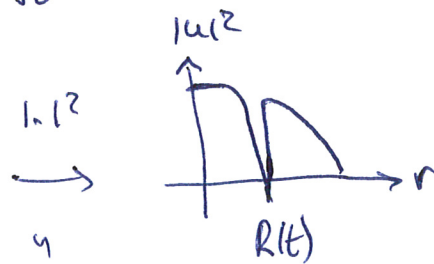
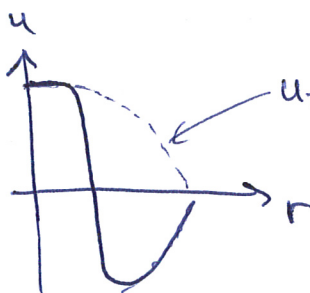
$N \uparrow$ if $\mu \uparrow$

- So if $N \gg 1 \Rightarrow \mu \gg 1$ and thus, for weak trap, $\Omega < 1$

$$\Rightarrow \mu \gg \frac{\Omega}{|r| < R_{TF}}$$

$$\Rightarrow u_{TF} \approx \sqrt{\mu - V} \approx \sqrt{\mu} - \frac{1}{2\sqrt{\mu}} (V) = \sqrt{\mu} - \frac{\Omega^2}{4\sqrt{\mu}} r^2 \quad (1.5)$$

- Let us now try to describe a dark soliton about the r -direction:



ie: a RING-DARK-SOLITON $\rightarrow$



- [PRL] ... $t \rightarrow \tau t$, $r \rightarrow \sqrt{\mu} r$ and use

$$u(\tau t) = \underbrace{u(r, t)}_{TF} \cdot v(r, t) \quad (1.5)$$

pert.

$$\text{in NLS} \Rightarrow i v_t + \frac{1}{2} v_{rr} - (|u|^2 - 1) v = P(v)$$

$$\text{where } P(v) = \frac{1}{\mu} \left[(1 - |u|^2) v + \frac{1}{2} v(r) v_r - \frac{\sqrt{\mu}}{2} v_r^2 \right] \quad (2)$$

$$\text{with } V(r) = \frac{\Omega^2}{2} r^2$$

and all terms on ~~the~~ $P(r)$ are of same order (small because $\mu \gg 1$) 94

∴ one can apply pert. theory for DS.

• DS (ring):
$$r(r,t) = \cos \varphi(t) \tanh z + i \sin \varphi(t) \quad (2.5)$$

$$z \equiv \cos(\varphi(t)) [r - R(t)]$$

 ↑ position of DS.

Perturbation

$$\frac{d\varphi}{dt} = \frac{\epsilon \ell e [1 - \frac{R}{2\mu} \frac{\partial \varphi}{\partial t} d_2]}{2 \cos^2 \varphi \sin \varphi}$$

+ (2) + (2.5)

$$\ddot{R} = \frac{1}{\epsilon \ell} (\sin \varphi) = \dot{\varphi} \cos \varphi$$

$$\Rightarrow \begin{cases} \frac{d\varphi}{dt} = -\frac{\cos \varphi}{2\mu} V'(R) + \frac{\cos \varphi}{3\sqrt{\mu} R} \\ \frac{dR}{dt} = \sin \varphi \Rightarrow \dot{R} = \sin \varphi \Rightarrow 1 - \dot{R}^2 = \cos^2 \varphi \end{cases}$$

$$\ddot{R} = \left[-\frac{1}{2} V'(R) + \frac{1}{3R} \right] [1 - \dot{R}^2] \quad (\mu = 1 \text{ for convenience})$$

• Suppose very slow DS: $\left| \frac{\dot{R}}{1} \right| = |\sin \varphi| \ll 1 \Rightarrow \frac{1 - \dot{R}^2}{\cos^2 \varphi} \approx 1$

$$\Rightarrow \ddot{R} = -\frac{1}{2} V'(R) + \frac{1}{3R}$$

• now consider a very large trap, $R \gg 1$

then the dynamics looks like: $\ddot{R} = -\frac{1}{2} V'(R)$

∴ know result for dynamics of DS stripe inside parabolic potential:



typo

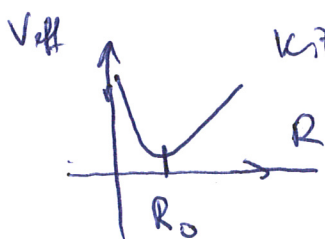
$$\Rightarrow \ddot{R} = -\frac{R}{2} \Rightarrow \ddot{R} = -\frac{1}{2} R \Rightarrow \frac{d}{dt} \left[\frac{1}{2} \frac{dR}{dt} \right] = -\frac{1}{2} R \Rightarrow \frac{d}{dt} \left[\frac{1}{2} \frac{dR}{dt} \right] = -\frac{1}{2} R$$

⇒ harmonic oscillation with freq $\frac{\omega}{\sqrt{2}}$

• Suppose slow DS but keep $1/3R$ ← this is "pressure" because of curvature effects of the ring.

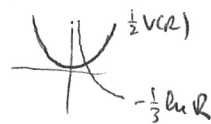
$$\ddot{R} = -\frac{1}{2} V'(R) + \frac{1}{3R}$$

Newton's law: $\ddot{R} = -\frac{1}{2} V'(R) + \frac{1}{3} [\ln R]' = -\frac{d}{dR} V_{\text{eff}}$



with $V_{\text{eff}} = \frac{1}{2} V(R) + \frac{1}{3} \ln R$

$$R_0: \frac{1}{2} V'(R_0) = \frac{1}{3} \frac{1}{R_0}$$



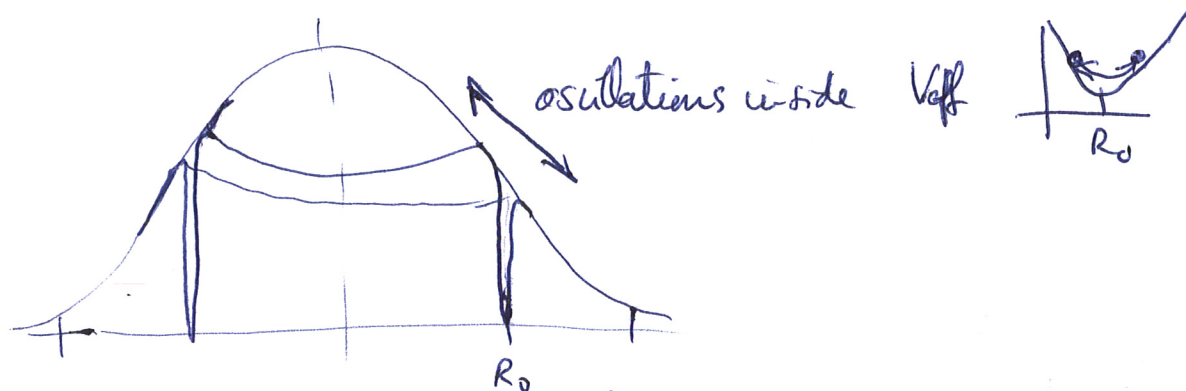
$R_0: V'_{\text{eff}}(R_0) = 0 \Rightarrow \frac{1}{2} \Omega^2 R_0 - \frac{1}{3 R_0} = 0 \Rightarrow R_0^2 = \frac{2}{3 \Omega^2}$

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$$\therefore \left| R_0 = \frac{\sqrt{2/3}}{\Omega} \right| \neq$$

and $R_{\text{TF}} = \frac{\sqrt{2\mu}}{\Omega} \stackrel{\mu=1}{=} \frac{\sqrt{2}}{\Omega} = \frac{\sqrt{2}}{\sqrt{3} \Omega} \sqrt{3} = R_0 \sqrt{3}$

$$\therefore \left| R_0 = R_{\text{TF}} / \sqrt{3} \right|$$



- We know that $\text{DS stripes are MI.}$ (see next)
- $\therefore$ If R becomes too large $\rightarrow$ MI

From top:



[See pics in PRL paper]

$\rightarrow$ generation of vortices.

Transverse stability of ^{Dark soliton stripes} plane solitons

[Kardar + Luther Davis = [1]
Phys. Rev. Lett. 298(98) 81-197]

90
87

follow a dark soliton stripe.

1D: $i u_t + \frac{1}{2} u_{xx} - |u|^2 u = 0$, $u(x,t) = u_0 [B \tanh(x+A)] e^{i \mu t}$

2D: $i u_t + \frac{1}{2} \nabla^2 u - |u|^2 u = 0$, $u(x,y,t) = u_0$

i.e. $u(x,y,t)$ is const w.r.t. y .

Transf:

$u = v e^{-i \mu t}$

NLS $\Rightarrow i(v_t + (-i\mu)v) + \frac{1}{2} \nabla^2 v - |v|^2 v = 0$
 $\Rightarrow i v_t + \frac{1}{2} \nabla^2 v + (\mu - |v|^2) v = 0$

$\mu = 1 \Rightarrow (1 - |v|^2) v$

This is done so that eq. with $(1 - |v|^2)$ has a stationary state with $\mu = 0$
 $\rightarrow$ i.e. No rotation in complex plane

Q: What is the stability of such object?

Rewrite DS stripe: $u_s = k \tanh[k(x-vt)] + i v$

$v = A u_0$

$k = B u_0$

for $u_0 = 1$

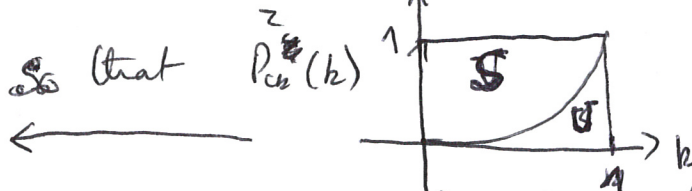
$v^2 + k^2 = 1$

and $0 \leq k \leq 1$

$\rightarrow$ It turns out that DS stripes are unstable to transverse

modes of the form $\sim \cos(py)$

For $P < P_c(k)$ and $P_c^2(k) = k^2 - 2 + 2\sqrt{k^4 k^2 + 1}$ ($v = \sqrt{1-k^2}$)



$P_c(k=0) = 0$

$P_c(k=1) = 1 - 2 + 2 = 1$

$\leftarrow$ So that $P_c^2(k)$ $\rightarrow$ I.e. it is ALWAYS unstable for very long wavelength

$\rightarrow$ However, in practice, as ~~we saw~~ for the experiment will always have finite length, so if we choose k small enough. ($k = B u_0 = u_0 \cos \phi$), namely $\phi \approx \pi/2$, i.e. very gray solitons then will be stable.

$[k = \frac{2\pi}{\lambda}]$

$\rightarrow$ For dark sol: $k = u_0 (=1$ in the above)

$\Rightarrow P_c^2(k=1) = 1 \therefore P_c = 1 \Rightarrow \lambda < 2\pi$

$\rightarrow$ See P. 180 in [1]: $\ominus \ominus \text{ (wavy line) } \leftarrow$ snake instability will be stable

- $$\Rightarrow i u_t + \frac{1}{2} \nabla^2 u - |u|^2 u = V_{MT} u$$

- $$\Rightarrow \boxed{u_t + \frac{1}{2} p^2 u - u u^2 = 0}$$

- $$\Rightarrow i v_t + \frac{1}{2} \nabla^2 u + (d - |v|^2)u = 0$$

$$\stackrel{ML}{\Rightarrow} i(v_{t\cancel{L}} - i\lambda v_{\cancel{L}}) + \frac{1}{2} \cancel{v_{\cancel{L}}}^2 \cdot \cancel{v_{\cancel{L}}} = 0$$

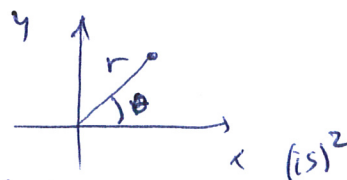
$$\Rightarrow (v_t + \frac{1}{2} \nabla^2 v + (\lambda - |v|^2) v = 0$$

-

$S \in \mathbb{Z}$ $\begin{matrix} S_0 \nearrow C \\ S_1 \searrow C \end{matrix}$

-



$$u(x,t) = \underbrace{R(r)}_r \underbrace{e^{i\theta}}_\theta \underbrace{e^{-i\omega t}}_t$$

$$iR\cancel{\phi}(-i\mu) + \frac{1}{2} \frac{1}{r} \partial_r (r \cancel{\phi} \cancel{\phi}^{\dagger}) + \frac{1}{2} \frac{1}{r^2} \partial_r^2 (r \cancel{\phi} \cancel{\phi}^{\dagger}) - R^3 \cancel{\phi} \cancel{\phi}^{\dagger} = 0$$

$$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$\Rightarrow +\mu R + \frac{1}{2r} \gamma_r(rR') + \frac{R}{2r^2}(-s^2) - R^3 = 0$$

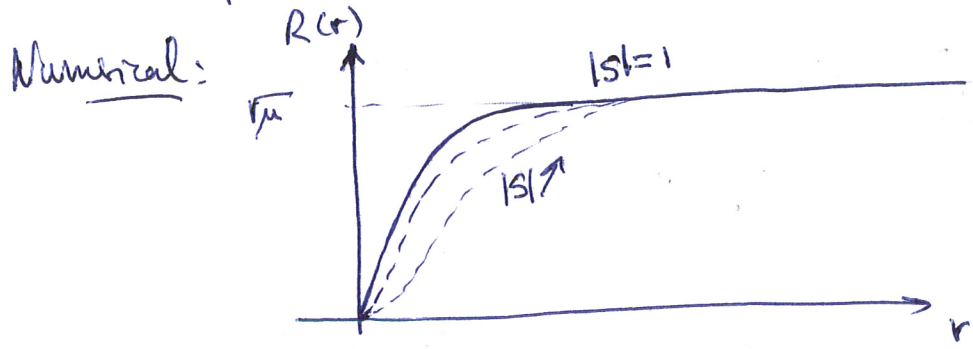
$$\Rightarrow \mu R + \frac{1}{2r} (R' + rR'') - \frac{R^2}{2r^2} - R^3 = 0$$

$$\Rightarrow \left| \frac{1}{2} R'' + \frac{1}{2r} R' + \left(\mu - \frac{R^2}{2r^2} \right) R - R^3 = 0 \right|$$

Need to solve this ODE with BCs: $R(0)=0$ & $R(\infty) = \sqrt{\mu}$

at $x=\infty$: $u = u_0 e^{i\phi} e^{-i\omega t} \Rightarrow \mu u_0 - u_0^3 = 0$
 $\Rightarrow u_0 (\mu - u_0^2) = 0 \Rightarrow \mu = u_0^2 \Rightarrow \boxed{u_0 = \sqrt{\mu}}$

⚠ the ODE for R does not have analytic solutions.
 * Not even for $S = \pm 1$



Shaw Hattels
 driver-sample-bvp

• Dynamics: vortex in a slow-varying inhomogeneous background:

Background } $\vec{v} \propto -S \hat{z} \times \nabla V$

potential = V } $\vec{v} \propto -S \hat{z} \times \nabla V \propto S \hat{z} \times \nabla \Phi$

~~$\vec{v} \propto -S \hat{z} \times \nabla \Phi$~~

~~$\vec{v} \propto -S \hat{z} \times \nabla V$~~

~~$\vec{v} \propto -S \hat{z} \times \nabla \Phi$~~

Where is $B(x,y)$ coming from? let us analyze NLS
 with linear potential:

steady state

$$\mu u(x) + \frac{1}{2} u_x^2 - u^3 = \alpha u$$

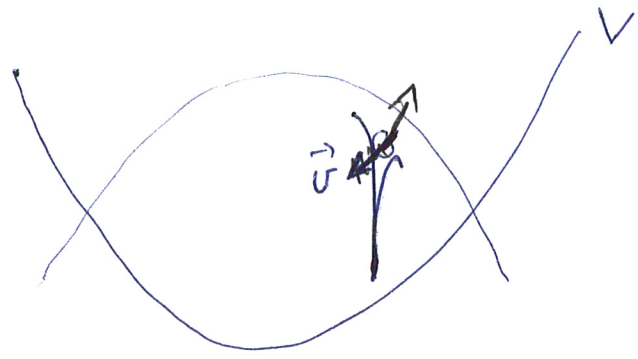
$$V(x) = \alpha x$$

$$u(x) = \beta x + \gamma$$

$$\Rightarrow \mu (\beta x + \gamma) - (\beta x + \gamma)^3 = \alpha (\beta x + \gamma)$$

$$= \mu - (\beta x + \gamma)^2 = \alpha x$$

thus, in a TF cloud:



In fact, more specific [Kivshin et al., Opt. Commun. 152 (98) 198-206]

$$\vec{u} = 2\nabla\theta_b + \underbrace{Ck \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}}_{R(\pi/2)} \nabla \ln I_b$$

$$k \equiv \ln \left(\frac{c \nabla_{\perp} I_b(\vec{r}_0) e^{i\theta}}{4} \right)$$

$C \equiv 1.126 \leftarrow$ found numerically

$\delta \equiv$ Euler const. $= \gamma = 0.577$

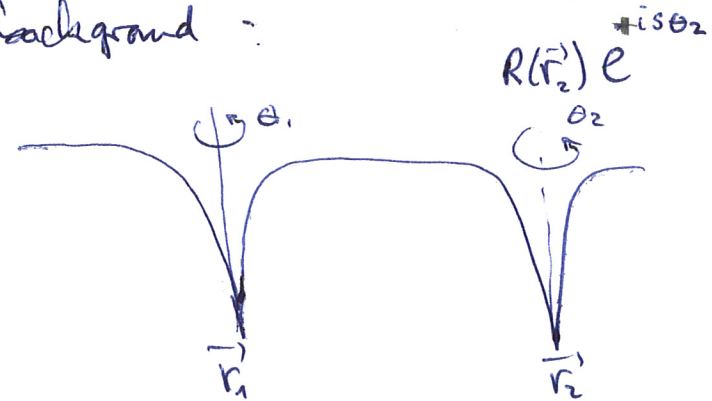
where background $= \sqrt{I_b} e^{i\theta_b}$

$\therefore$ $\left\{ \begin{array}{l} \text{phase gradients} \rightarrow \vec{u} \parallel \text{phase gradient} \\ \text{Intensity gradients} \rightarrow \vec{u} \perp \text{Intensity gradient} \end{array} \right.$

Δ the above analysis is valid for weakly varying backgrounds.

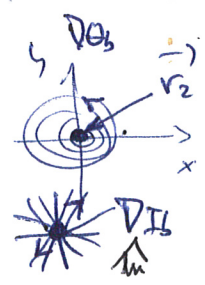
Vortex-vortex interactions:

take one vortex and view the other as a perturbation to the background:

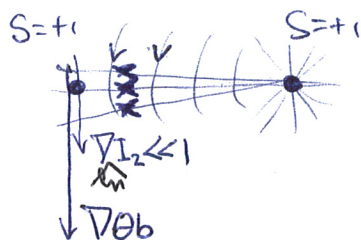


- the second vortex produces a phase gradient
- the second vortex produces an intensity gradient:

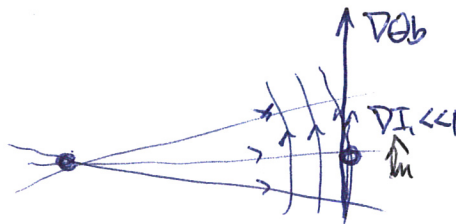
$\therefore$ since $\vec{u} \parallel \nabla\theta_b$ & $\vec{u} \perp \nabla I_b$
 $\Rightarrow$ all velocities are ~~radial~~ Azimuthal!!!



Same charge



and vice-versa



2 vortices with same charge: will rotate with const. ang. velocity.



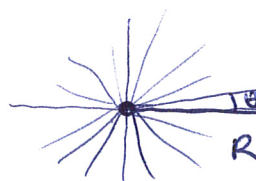
opposite charge
(V_I 's $\ll 1$
so neglected)



2 vortices with same charge will ~~rotate~~ move parallel to each other with constant speed

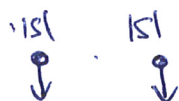
Rates for velocities :

$\Theta_b \hat{=}$



$$\therefore \|V_{\Theta_b}\| \approx \frac{1}{R}$$

2 opposite charge



$$V_{lin} \propto \frac{|S|}{R}$$

$$V_{ang} \propto \frac{|S|}{R^2}$$



Strac all parts of dynamics for vortices from Research review.

$$\Theta_b = \tan^{-1} y/x$$

$$\Rightarrow V_{\Theta_b} = \left(\frac{\partial \Theta}{\partial x}, \frac{\partial \Theta}{\partial y} \right) = \left(-\frac{y}{x^2 + y^2}, \frac{x}{x^2 + y^2} \right)$$

$$= \left(-\frac{y}{R^2}, \frac{x}{R^2} \right) \approx \frac{R^4}{R^2} \propto 1/R$$

$$\therefore \|V_{\Theta_b}\|^2 = \frac{y^2}{R^4} + \frac{x^2}{R^4} = \frac{R^2}{R^4} = \frac{1}{R^2}$$

$$\therefore \|V_{\Theta_b}\| = \frac{1}{R}$$



$$x(t) = R \Theta(t) \Rightarrow \Theta(t) = \frac{x(t)}{R}$$

$$\dot{\Theta} = \frac{\dot{x}}{R} = \frac{V}{R}$$

$$\text{but } V \propto \frac{1}{R} \Rightarrow \dot{\Theta} \propto \frac{1}{R^2}$$

Numerical techniques:

- Steady States $\Rightarrow$ Newton method in high D
- Stability $\Rightarrow$ eigenvalue problem.

Steady States:

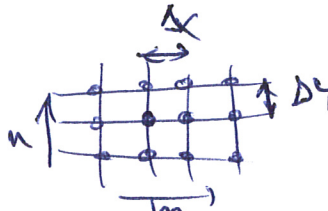
* Suppose $u_t = F(u, u_x, u_{xx}, u_y, u_{yy}, u_{xy}, \dots)$

is a time dependent PDE.

We want to find u^* such that $u_t = 0$, i.e. $F(\dots) = 0$

$\rightarrow$ Finding a zero of an ODE system $\rightarrow$ Newton method.

* First, let us turn our ODE system into a finite one by discretizing derivatives:

$$u(x, y, t) \rightarrow u_{m,n}(t)$$


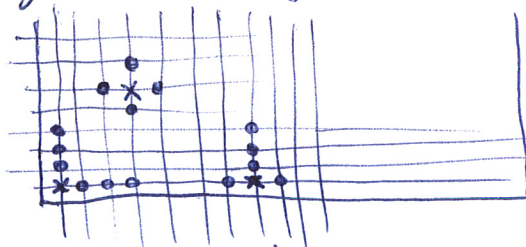
$$u_x = \frac{u_{m+1,n} - u_{m-1,n}}{2\Delta x} + O(\Delta x^2)$$

$$u_{xx} = \frac{u_{m+1,n} - 2u_{m,n} + u_{m-1,n}}{\Delta x^2} + O(\Delta x^2)$$

$$\nabla^2 u = u_{xx} + u_{yy} = \frac{1}{\Delta^2} (u_{m+1,n} + u_{m-1,n} + u_{m,n+1} + u_{m,n-1} - 4u_{m,n}) + O(\Delta^2)$$

discrete Laplacian.

• At boundaries you can use forward and backward differences.



* Thus, after discretization we have:

$$\frac{d}{dt}(u_{m,n}) = F(u's)$$

$\rightarrow$ steady state becomes $F(u's) = 0$

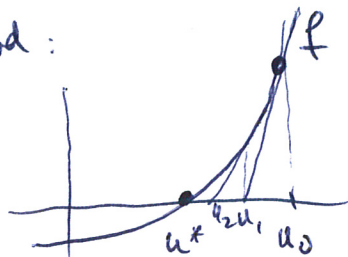
where $\vec{u} = (u_{1,1}, u_{2,1}, \dots, u_{N,1}, u_{1,2}, \dots, u_{N,2}, \dots, u_{N,N})$

i.e. all values of u unwrapped in a vector:

$$F(\vec{u}) = 0$$

* Newton method:

2D:



$$u^{n+1} = u^n - \frac{f(u^n)}{f'(u^n)}$$

1D: Use Taylor to find formula:

Find $F(u^*) = 0$ from initial guess u^0
If we are close: $\Delta u = u^* - u^0$ is small
and thus:

$$F(u^*) = 0 \Rightarrow F(u^0 + \Delta u) = 0$$

$$\Rightarrow F(u^0) + J(u^0) \cdot \Delta u + \dots = 0$$

$$\Rightarrow F(u^0) + J(u^0) (u^* - u^0) \approx 0$$

$$\Rightarrow u^* \approx u^0 - J^{-1}(u^0) F(u^0)$$

So, we do this in iterates:

$$u^{n+1} = u^n - J^{-1}(u^n) F(u^n)$$

Newton in higher D.

* For NLS: Δ In practice $\rightarrow$ do NOT invert Jacobian (it is expensive $O(N^3)$)
* Just solve linear problem $J \Delta u = F$ for $\Delta u = u^{n+1} - u^n$

$$i u_t + \nabla^2 u \pm |u|^2 u = V \cdot u.$$

$$u_t = v e^{-i\mu t} \text{ st-st.}$$

$$\mu v + \nabla^2 v \pm |v|^2 v = V \cdot v$$

$$\Rightarrow F(v) = [\mu - V] + \nabla^2 \pm |v|^2 v = 0$$

$\Rightarrow$ Newton method. discrete Laplacian

* Show sample in Matlab
be2d with driver.

Jacobian: If $v_n \in \mathbb{C}$ then one has to split real and imaginary part of Jacobian
 $\rightarrow$ this is what needs to be done for vortices for example

$$\text{in 1D: } \nabla^2 u_n = \frac{u_{n-1} - 2u_n + u_{n+1}}{\Delta x^2}$$

$$\therefore J = (\mu - V \pm 3|v_n|^2) v_n \mathbb{I} + \frac{1}{\Delta x^2} \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$$

$\uparrow$ if $|v_n|^2 = v_n^2$ (i.e. real solution)

but if $v_n \in \mathbb{C}$: $v = v^0 + \epsilon w \Rightarrow |v|^2 v = v^2 v = (v^0 + \epsilon w)^2 (v^0 + \epsilon w) = (v^0^2 + 2\epsilon v^0 w + \epsilon^2 w^2)(v^0 + \epsilon w)$
 $= v^0^3 + \epsilon [2v^0^2 w + v^0 w^2] + O(\epsilon^2)$

* $J = (\mu - V \pm 2|v_n|^2) v_n$ linearization.

Stability:

- In many occasions, it is not possible to do a linear stability analysis analytically. For example, for ~~the~~ vortex sol the sol itself cannot be found analytically so one cannot ~~do~~ do the stab. analysis
- Let us concentrate in NLS, for other PDEs it is similar.

* Eq: $i u_t + \frac{1}{2} \nabla^2 u \pm |u|^2 u = V u$

* steady state $u = u^0 e^{-i\mu t} \Rightarrow \mu u^0 + \frac{1}{2} \nabla^2 u^0 \pm |u^0|^2 u^0 - V u^0 = 0$

* Newton $\rightarrow$ find steady state u^0 .

* stability take $u = u^0 e^{-i\mu t}$ and perturb:

~~* Discretize and vectorize:~~
 ~~$u = u^0 + \epsilon (a e^{it} + b e^{-it})$~~
 ~~$u_n(t) = u_n^0 + \epsilon (a_n e^{it} + b_n e^{-it}) = u_n^0 + \epsilon w_n(t)$~~
~~NLS $\Rightarrow i [2 u_n]$~~

$$u = [u^0 + \epsilon (a e^{it} + b e^{-it})] e^{-i\mu t}$$

* Discretize and vectorize:

$$u(x,t) = v(x,t)$$

$$u_n(t) = [u_n^0 + \epsilon (a_n e^{it} + b_n e^{-it})] e^{-i\mu t} = (u_n^0 + \epsilon v_n) e^{-i\mu t}$$

$$\text{NLS} \Rightarrow i [\epsilon \dot{v}_n + (u_n^0 + \epsilon v_n) \epsilon] + \frac{1}{2} \nabla^2 (u_n^0 + \epsilon v_n) + \alpha |u_n^0 + \epsilon v_n|^2 (u_n^0 + \epsilon v_n) - V_n (u_n^0 + \epsilon v_n) = 0$$

now expand $|u_n^0 + \epsilon v_n|^2 (u_n^0 + \epsilon v_n) = (u_n^0 + \epsilon v_n)^2 (\bar{u}_n^0 + \epsilon \bar{v}_n) = (u_n^0^2 + 2\epsilon u_n^0 v_n + \epsilon^2 v_n^2) (\bar{u}_n^0 + \epsilon \bar{v}_n)$
 $= \underbrace{|u_n^0|^2 u_n^0} + 2\epsilon |u_n^0|^2 v_n + \epsilon u_n^0^2 \bar{v}_n + O(\epsilon^2)$

now = steady state

$$\Rightarrow i \dot{v}_n + \mu v_n + \frac{1}{2} \nabla^2 v_n + \alpha 2 |u_n^0|^2 v_n + \alpha u_n^0^2 \bar{v}_n - V_n v_n = 0$$

$$\Rightarrow i \dot{v} + \mu v + \frac{1}{2} \nabla^2 v + 2\alpha |u^0|^2 v + \alpha u^0^2 \bar{v} - V v = 0$$

Remember $v_n = a_n e^{it} + b_n e^{-it}$

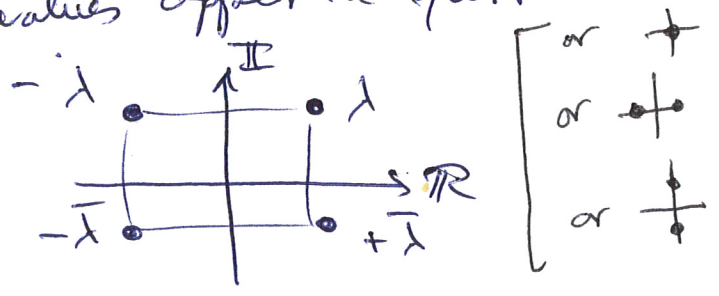
$$\Rightarrow i (\dot{a}_n e^{it} + \dot{b}_n e^{-it}) + \mu (a_n e^{it} + b_n e^{-it}) + 2\alpha |u^0|^2 (a_n e^{it} + b_n e^{-it}) + \alpha u^0^2 (\bar{a}_n e^{-it} + \bar{b}_n e^{it}) - V (a_n e^{it} + b_n e^{-it}) = 0$$

$$\rightarrow e^{it} \left[i\lambda a + \mu a + \frac{1}{2} \nabla^2 a + 2\alpha |u|^2 a + \alpha u^2 \bar{b} - V a \right] + e^{i\bar{t}} \left[i\bar{\lambda} b + \mu b + \frac{1}{2} \nabla^2 b + 2\alpha |u|^2 b + \alpha u^2 \bar{a} - V b \right] = 0 \quad (1)$$

but e^{it} and $e^{i\bar{t}}$ are linearly independent $\Rightarrow \begin{cases} \begin{bmatrix} \cdot \\ \cdot \end{bmatrix} = 0 \\ \begin{bmatrix} \cdot \\ \cdot \end{bmatrix} = 0 \end{cases} \Leftrightarrow \underbrace{M \vec{w} = \lambda \vec{w}}_{\text{eigenval. pb.}}$

Invariances: ① if $\lambda \leftrightarrow \bar{\lambda}$ and $a \leftrightarrow b \Rightarrow$ eqns unchanged, so if λ is sol. so is $\bar{\lambda}$
 ② if $\lambda \leftrightarrow -\lambda$ and $a \leftrightarrow \bar{a}$ & $b \leftrightarrow \bar{b} \Rightarrow$ eqns unchanged, so if λ is sol. so is $-\lambda$

$\therefore$ eigenvalues appear in quartets:



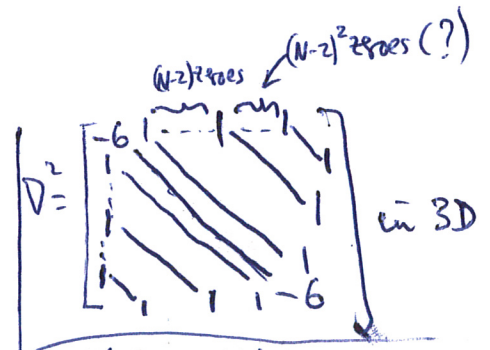
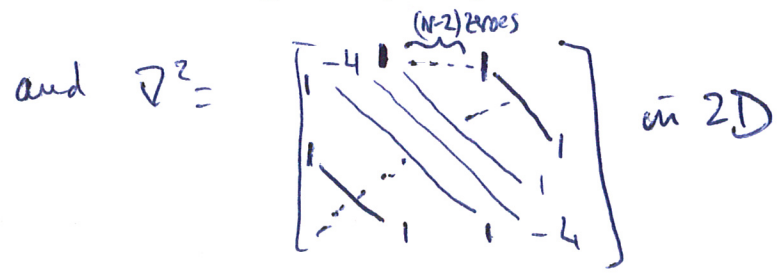
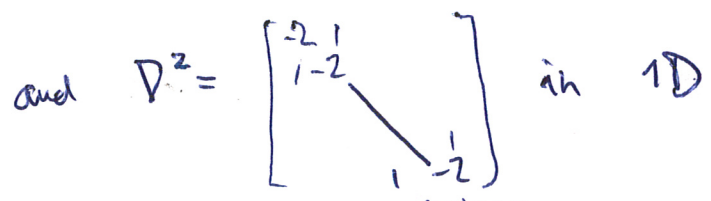
Eigenvalue problem: $M \vec{w} = \lambda \vec{w}$

$$\begin{aligned} (1) a \neq 0 &\Rightarrow \begin{cases} \lambda a = i \left[\mu a + \frac{1}{2} \nabla^2 a + 2\alpha |u|^2 a + \alpha u^2 \bar{b} - V a \right] \\ \lambda \bar{b} = i \left[\mu \bar{b} + \frac{1}{2} \nabla^2 \bar{b} + 2\alpha |u|^2 \bar{b} + \alpha \bar{u}^2 a - V \bar{b} \right] \end{cases} \\ (2) b \neq 0 &\Rightarrow \end{aligned}$$

$\therefore$ if $\vec{w} = \begin{pmatrix} a \\ \bar{b} \end{pmatrix}$ & M :

$$M = i \begin{pmatrix} \begin{matrix} a & \bar{b} \\ \mu - V + 2\alpha |u|^2 + \frac{1}{2} \nabla^2 & \alpha u^2 \\ -\alpha \bar{u}^2 & -(\mu - V + 2\alpha |u|^2) - \frac{1}{2} \nabla^2 \end{matrix} \end{pmatrix}$$

$$= i \begin{bmatrix} M_{11} & M_{12} \\ -\bar{M}_{12} & -M_{11} \end{bmatrix} \quad \begin{matrix} M_{11} \in \mathbb{R}^{N \times N} \\ M_{12} \in \mathbb{C}^{N \times N} \end{matrix}$$



Shaw wallah
 $N = 80 \times 50$ $\Omega = 0.05$
 $\text{Eigs} = 100$, $\sigma = 0.5$
 Vortex = $S=1, S=2, S=3, S=4$

Instabilities for 2D

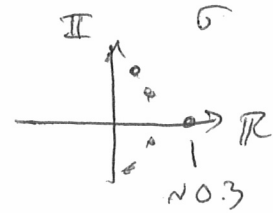
- * A $S=\pm 1$ vortex will always stable @ (0,0) of V_{HT}
- * Higher order vortices are unstable in some parameter windows $\rightarrow$ [H. Du et al. PRA 59 (1999) ~~4438~~ 1533]



* Numbers [See-newton-stability.zip]

$$S=+3, N=100, \Omega=0.025 \rightarrow$$

~~σ_{max}~~



Dynamical reduction for vortices in BECs

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When vortices are trapped there will be 2 contributions to eq-of-motion:

- Vortex-trap interaction
- Vortex-vortex interactions

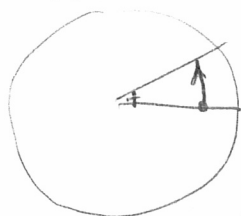
If we assume a) & b) are independent then we can just add these two contributions.

a) Vortex-trap interactions

Many ways to find this (usually in the TF limit):
variational, perturbation, energetic, ...

[Refs: see nonlinear / ... / notebook / references / vortex-precession / notes.txt]

* Trap $\rightarrow$ approx. constant precession / ang. vel.



$w_{pr} = w_{pr}^0$ (precession @ center)

$w_{pr}^0 = w_{pr}^0(\mu, \Omega)$ $\leftarrow$ trap strength
chem. potential

* correction (Fetter):

$$w_{pr} = \frac{w_{pr}^0}{(1 - \frac{r^2}{R_{TF}^2})}$$

* even better correction: [Fetter PRA 89 (14) 023629
 $\rightarrow$ paper is in 2D but precession for 1D can be extracted from it]

b) Vortex-vortex:

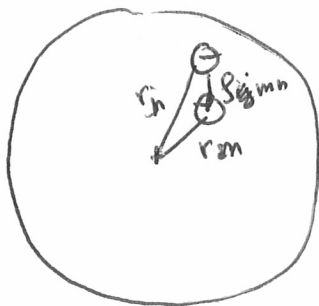


$$v_{lin} \propto \frac{1}{S_{ij}^{1/2}}$$



$$w_{ij} \propto \frac{1}{S_{ij}^{1/2}}$$

Combining the 2:



$$\begin{aligned} \dot{x}_m &= -S_m w_{pr} y_m \\ \dot{y}_m &= -S_m w_{pr} x_m \end{aligned}$$

$$\Rightarrow \ddot{x}_m = -S_m w_{pr} \dot{y}_m = S_m^2 w_{pr}^2 x_m$$

$$\Rightarrow \text{ang. vel} = S_m w_{pr}$$

$$\begin{aligned} \dot{x}_m &\propto -S_m \frac{y_m - y_n}{S_{ij}^{1/2}} \\ \dot{y}_m &\propto +S_m \frac{x_m - x_n}{S_{ij}^{1/2}} \end{aligned}$$

Considering N vortices with position (x_i, y_i) & charge S_i we get

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$$(1) \begin{cases} \dot{x}_m = -S_m \omega_r y_m + \frac{\omega_{int}}{2} \sum_{n \neq m} S_n \frac{y_m - y_n}{p_{mn}^2} \\ \dot{y}_m = -S_m \omega_r x_m + \frac{\omega_{int}}{2} \sum_{n \neq m} S_n \frac{x_m - x_n}{p_{mn}^2} \end{cases}$$

$S_j \frac{\omega_{int}}{p_{mn}^2} = \text{ang. vel. of 2 vortices separated by } p_{mn}$

Conserved quantities:

1) Total energy = Hamiltonian:

$$H = -\frac{\omega_r}{2} \sum_{m=1}^N \ln(1+r_m^2) + \frac{\omega_{int}}{4} \sum_{m \neq n} S_m S_n \ln(p_{mn}^2)$$

2) Ang. momentum = L

$$L = \sum_{m=1}^N S_m r_m^2$$

Complex version of eq. of motion:

$$z_m = x_m + i y_m$$

$$\dot{z}_m = -i S_m \omega_r z_m + i \frac{\omega_{int}}{2} \sum_{n \neq m} \frac{z_m - z_n}{|z_m - z_n|^2}$$

→ give the talk about vortices & $\mathcal{K}_1$ in V_{MT}
(++, +-, pitchfork, etc, ...)

Nonlinear lattices

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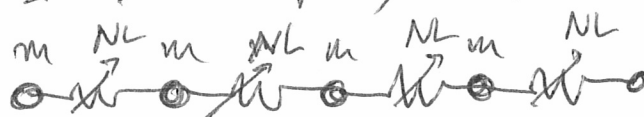
FPU

Fermi-Pasta-Ulam [Los Alamos report 1955] [FPU in Scholpedia]

- Nonlinear lattice to model the thermalization of a solid $\rightarrow$ i.e. equipartition of energy in all modes
- A linear lattice has dynamics that is the linear combo of the normal modes of vibration
- nonlinearity $\Rightarrow$ ~~connection~~ ^{coupling} between $\neq$ modes
 $\Rightarrow$ energy transfer between $\neq$ modes
 $\Rightarrow$ thermalization

- Numerical experiments using one of the first computers (Mainiac)

model = linear spring-masses + small nonlinearity:



$m=1$

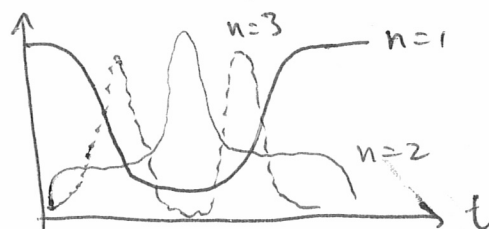
$\Rightarrow$

$k=1$
Linear

$$\ddot{u}_n = \underbrace{u_{n+1} - 2u_n + u_{n-1}}_{\substack{+k(u_{n+1}-u_n) \\ -k(u_{n-1}-u_n)}} + \alpha [(u_{n+1}-u_n)^2 - (u_n-u_{n-1})^2]$$

- Surprise when they ran model:

$E_n \leftarrow$ energy of n -th mode



$\rightarrow$ Recurrence

Shaw
Matlab
FPU.m

- * For short time $\rightarrow$ almost equipartition
- * by mistake they ran it for longer & after ~ 157 periods of mode 1 the $n=1$ recovered 97% of its energy !!!

$\rightarrow$ nonlinearity is not sufficient to thermalize

why? Not equipartition?

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→ solitons!

show kink-antikink solution

Katlas

where are these solitons coming from?

A → continuum limit approx. of FPU → KdV !!

Toda lattice

- let us study in more detail a nonlinear lattice that can be solved analytically → Toda lattice (TL)

[Non-linear wave propagation in the 1D TL, Tai Aoki]
+ [M-Toda J. Phys. Soc. Japan 22 (1967) 431]

- Toda introduced this model so that it could be solved analytically.

$$m_n \ddot{y}_n = -\phi'(y_n - y_{n+1}) + \phi'(y_{n-1} - y_n)$$



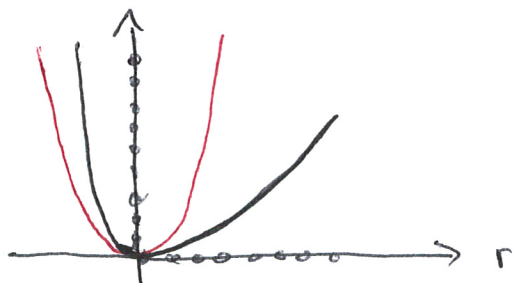
ϕ : potential interaction → $F = -\frac{\partial \phi}{\partial y}$

potential: $\phi(r) = \frac{a}{b} e^{-b(r-\sigma)} + ar + \text{const.}$

• $ab > 0$

• $r \rightarrow r - \sigma$ same eq. with $\neq \text{const}$

∴ $\sigma = 0$ without loss of generality.



limits: (a) $b \rightarrow 0$ & $ab = \text{const}$

→ ~~linear~~ $\phi \propto r^2$ U

→ linear force

(b) $b \rightarrow \infty$ & $ab = \text{const}$

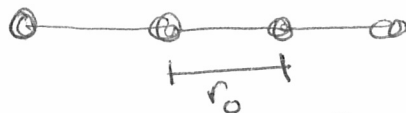
→ ϕ is hard sphere L

Dual lattice representation

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Newton $\rightarrow$
 $m_n = m$

$$m \ddot{y}_n = a e^{-b(y_n - y_{n-1} - r_0)} - a e^{-b(y_{n+1} - y_n - r_0)} \quad (1)$$



r_0 equilibrium distance.

Def: perturbation away from equilibrium:

$$r_n \equiv y_n - y_{n-1} - r_0 \quad (2)$$

$$\Rightarrow \ddot{r}_n = \ddot{y}_n - \ddot{y}_{n-1} = \frac{a}{m} e^{-b r_n} - \frac{a}{m} e^{-b r_{n+1}} - \frac{a}{m} e^{-b r_{n-1}} + \frac{a}{m} e^{-b r_n}$$

$$\Rightarrow m \ddot{r}_n = a [2e^{-b r_n} - e^{-b r_{n+1}} - e^{-b r_{n-1}}]$$

this looks like a discrete Laplacian.

Def: $s_n \equiv a [e^{-b r_n} - 1] \quad (3)$

$$\Rightarrow a e^{-b r_n} = s_n + a$$

$$\Rightarrow m \ddot{r}_n = a [2(s_n + a) - (s_{n+1} + a) - (s_{n-1} + a)]$$

$$= a [2s_n - s_{n+1} - s_{n-1}] \Rightarrow m \ddot{r}_n = a [2s_n - s_{n+1} - s_{n-1}]$$

but $r_n \equiv y_n - y_{n-1}$

$$\Rightarrow m \ddot{y}_n = s_n - s_{n-1} \Rightarrow m \ddot{y}_n = s_n - s_{n-1}$$

and $s_n = -ab r_n e^{-b r_n}$

$$= -ab r_n [e^{-b r_n} - 1 + 1] = -b r_n [s_n + a]$$

$$\Rightarrow \left[\frac{\ddot{s}_n}{s_n + a} = -\frac{b}{m} (2s_n - s_{n+1} - s_{n-1}) \right] \quad (4)$$

Sol: $\frac{d}{dt} \left[\ln \left(1 + \frac{s_n}{a} \right) \right] = \frac{\dot{s}_n}{a} \cdot \frac{1}{1 + \frac{s_n}{a}} = \frac{\dot{s}_n}{a + s_n}$

$\therefore$ Def $p_n = \int s_n dt$ [or $s_n = \dot{p}_n$]

$$\Rightarrow \frac{d}{dt} \left[\ln \left(1 + \frac{\dot{p}_n}{a} \right) \right] = -\frac{b}{m} [2 \dot{p}_n - \dot{p}_{n+1} - \dot{p}_{n-1}]$$

$$\text{Sat} \Rightarrow \boxed{\ln \left(1 + \frac{\ddot{P}_n}{a} \right) = -\frac{b}{u} (2P_n - P_{n-1} - P_{n+1})} \quad (5)$$

using this expression and the fact that

$$\begin{aligned} [\tanh]' &= 1 - \tanh^2 \\ \int \tanh &= \ln(\cosh) \\ &= \ln\left(\frac{1}{\text{sech}}\right) \end{aligned}$$

one can prove that the following is a solution for (5) by using $S_n = \pm \frac{\beta^m}{b} \tanh(uk \pm \beta t) + \text{const.}$

$$\boxed{\ln \left[1 + \frac{\beta^{2m}}{ab} \text{sech}^2(uk \pm \beta t) \right] = -b r_n} \quad (6)$$

sech-soliton solution !!!

$$v = \beta/k$$

Show Matlab
A=1, A=0.1

Discrete NLS (DNLS)

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[Carretero's paper #59]

[Intro]

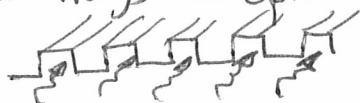
Discrete versions of the NLS, i.e. DNLS, emerge from several applications:

* periodic potentials in BECs:



- using suitable basis (Wannier functions)
→ coupled ODE's on params $\Rightarrow$ DNLS

* Waveguide arrays in optics



* photorefractive media

* DNLS is a prototypical model for envelope waves in discrete media

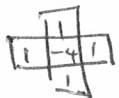
[DNLS]

$$\boxed{i \dot{U}_n = -\epsilon \Delta U_n + \beta |U_n|^2 U_n} \quad (1) \quad \{U_n\}_{n=-\infty}^{\infty} \quad \epsilon, \beta \in \mathbb{R}$$

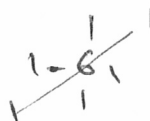
← discrete Laplacian

1D $\Delta U_n = U_{n-1} - 2U_n + U_{n+1}$

2D



3D



[Steady states] ~~Asymptotic states~~

Sep. var. $U_n = v_n e^{i\lambda t} \quad (2)$

(2) $\Rightarrow -\lambda v_n = -\epsilon \Delta v_n + \beta |v_n|^2 v_n$

* in 1D one can prove that $v_n \in \mathbb{R}$

$\Rightarrow \lambda v_n = \epsilon \Delta v_n - \beta v_n^3$

$\boxed{\lambda v_n = \epsilon (v_{n-1} - 2v_n + v_{n+1}) - \beta v_n^3} \quad (3) \text{ Recurrence relationship}$

• This second order recurrence: $G(v_n, v_{n-1}, v_{n+1}) = 0$
can be cast as $2 \times 1^{\text{st}}$ order recurrences:

[Same way as transf. a $1 \times 2^{\text{nd}}$ order ODE $\rightarrow 2 \times 1^{\text{st}}$ order ODE : i.e. intermediate variable.

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$$W_n \equiv V_{n-1}$$

$$(3) \Rightarrow \quad \cancel{w} \quad V_{n+1} = -\varepsilon W_n + (\lambda + 2\varepsilon X) V_n + \beta V_n^3$$

$$\Rightarrow \quad \boxed{\begin{cases} V_{n+1} = \frac{1}{\varepsilon} [(\lambda + 2\varepsilon) V_n - \varepsilon W_n + \beta V_n^3] \\ W_{n+1} = V_n \end{cases}} \quad \begin{array}{l} 2D \\ \text{recurrence.} \end{array}$$

$$\Leftrightarrow \quad 2D \text{ Map:} \quad \begin{pmatrix} V_{n+1} \\ W_{n+1} \end{pmatrix} = M \begin{pmatrix} V_n \\ W_n \end{pmatrix}$$

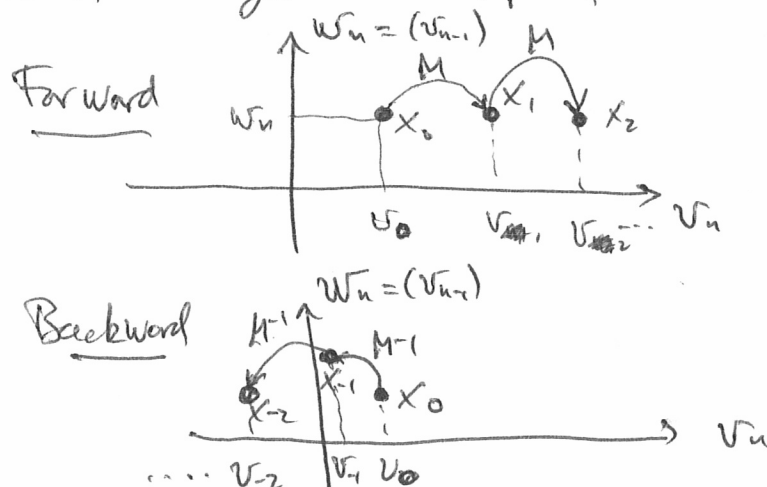
$$M: \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} \frac{1}{\varepsilon} [(\lambda + 2\varepsilon)x - \varepsilon y + \beta x^3] \\ x \end{pmatrix}$$

∴ Every stationary state $U_n = V_n e^{i k t}$ must come from an orbit of the 2D Map M

* We need 2 ICs :

$$\text{IC } X_0 = \begin{pmatrix} V_0 \\ W_0 \end{pmatrix} \text{ and to get}$$

* We then need to iterate forward & backward in n to get the shape of the whole lattice:



this way we get: $\{\dots, V_{-2}, V_{-1}, V_0, V_1, V_2, \dots\}$

⊙ M & M^{-1} are identical after $U_n \leftrightarrow W_n$
 $\Rightarrow$ Forward & backward orbits are symmetric
w.r.t. $y=x$ line!

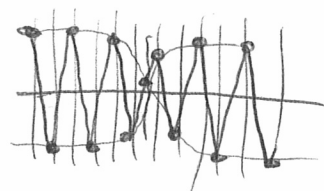
⊙ Exchanging $U_n \rightarrow (-1)^n U_n$ (and thus $W_n \rightarrow (-1)^n W_n$),
i.e. using the so-called STAGGERING TRANSF, the
map transf. $M \rightarrow (-1)^n M$ with $\begin{cases} \lambda \rightarrow -\lambda - 4\epsilon \\ \beta \rightarrow -\beta \end{cases}$

∴ one can go from attractive/focusing ($\beta < 0$)
to repulsive/defocusing ($\beta > 0$) nonlinearities
by just alternating signs of the U 's!

Ex: $\beta < 0 \rightarrow$ attractive $\rightarrow$ bright soliton

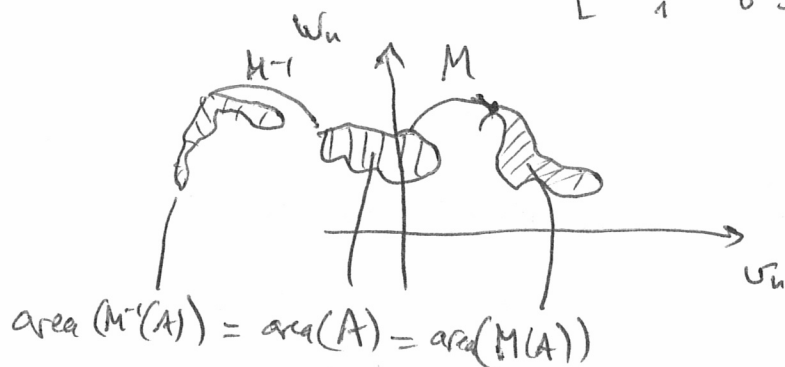


* staggering with $\beta < 0$ is equivalent to repulsive
 $\rightarrow$ dark soliton $\rightarrow$



⊙ M is area preserving: $\det(M) = 1$

proof: $J(M) = \begin{bmatrix} \frac{1}{\epsilon}(\lambda + 2\epsilon) + \beta U_n & -\frac{1}{\epsilon} \\ 1 & 0 \end{bmatrix} \Rightarrow |J(M)| = 1 \Rightarrow$ area preserv.



Consequences:

- linear centers are nonlinear centers
i.e. linear stab. is enough
- W^s & W^u for saddles must have
must have same rates of attraction/repulsion.

Different steady states

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Homogeneous : $\begin{cases} u_{n+1} = v_n \\ w_{n+1} = w_n \end{cases}$ i.e. fixed pts.

but $\begin{cases} w_{n+1} = v_n \\ w_n = v_{n-1} \end{cases} \Rightarrow \begin{cases} v_{n+1}^* = v_n^* \\ v_n^* = v_{n-1}^* \end{cases}$

$\Rightarrow \text{fixed pts} \Rightarrow v_n = \{\dots, v_n^*, \dots\}$
and $w_n = \{\dots, v_{n-1}^*, \dots\}$

$\therefore$ fixed pts need to be on $y=x$ line.

$\Delta (3) \Rightarrow \lambda v_n^* = \varepsilon (v_n^* - 2v_{n-1}^* + v_{n-2}^*) - \beta (v_n^*)^3$
[$\Delta=0$ because homogeneous!]]

$\Rightarrow v_n^* (\lambda + \beta v_n^{*2}) = 0$

$\Rightarrow v^* = \begin{cases} 0 \\ \pm \sqrt{-\lambda/\beta} \end{cases}$

$\therefore$ Homogeneous steady states : $\begin{cases} u_n = 0 e^{i\lambda t} = 0 \\ u_n = \pm \sqrt{-\lambda/\beta} e^{i\lambda t} \end{cases}$

* condition for nontrivial fpts: $\lambda/\beta < 0$

Phase portrait: We need stability for fpts:

$v^* = 0$ $J = \begin{bmatrix} \frac{1}{\varepsilon}(\lambda + 2\varepsilon) + 3\beta v_n^0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\varepsilon}(\lambda + 2\varepsilon) & -1 \\ 1 & 0 \end{bmatrix}$

lig(J): $|J - \mu I| = 0 \Rightarrow (\frac{1}{\varepsilon}(\lambda + 2\varepsilon) - \mu)(-\mu) + 1 = 0$

$\Rightarrow \mu^2 + \frac{1}{\varepsilon}(\lambda + 2\varepsilon)\mu + 1 = 0$

$\Rightarrow \mu_{\pm} = \frac{-\frac{1}{\varepsilon}(\lambda + 2\varepsilon) \pm \sqrt{\frac{(\lambda + 2\varepsilon)^2}{\varepsilon^2} - 4}}{2}$

$\therefore$ If $D = \frac{(\lambda + 2\varepsilon)^2}{\varepsilon^2} - 4 \Rightarrow D < 0$

$= \frac{1}{\varepsilon^2} [\lambda^2 + 4\varepsilon\lambda + 4\varepsilon^2 - 4\varepsilon^2]$

$= \frac{1}{\varepsilon^2} \lambda (\lambda + 4\varepsilon)$

$$\therefore \mu_{\pm} = \frac{\lambda + 2\varepsilon \pm \sqrt{\lambda(\lambda + 4\varepsilon)}}{2\varepsilon}$$

~~020~~

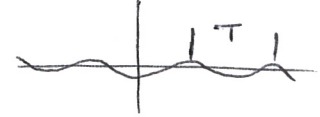
$D < 0$: complex evals : $\mu_{\pm} = \frac{1}{2\varepsilon} [\lambda + 2\varepsilon \pm \sqrt{\lambda(\lambda + 4\varepsilon)}]$

$$|\mu|^2 = \left(\frac{1}{2\varepsilon}\right)^2 [(\lambda + 2\varepsilon)^2 + (-\lambda(\lambda + 4\varepsilon))]$$

$$= \left(\frac{1}{2\varepsilon}\right)^2 [\cancel{\lambda^2} + 4\varepsilon\lambda + 4\varepsilon^2 - \cancel{\lambda^2} - 4\varepsilon\lambda] = \frac{4\varepsilon^2}{4\varepsilon^2} = 1$$

$\therefore |\mu|^2 = 1 \Rightarrow$ center 

freq $\approx \text{Im}(\mu) = \frac{1}{2\varepsilon} \sqrt{-\lambda(\lambda + 4\varepsilon)}$

$\therefore$ period $T \approx \frac{2\pi}{\text{freq.}}$ 

provided perturbation from $V \approx 0$ is small.

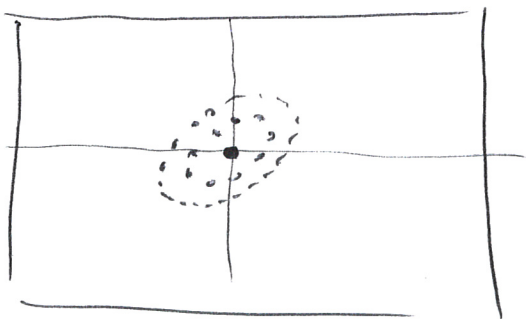
$D > 0$: Real evals : $\mu_{\pm} = \frac{1}{2\varepsilon} [\lambda + 2\varepsilon \pm \sqrt{\lambda(\lambda + 4\varepsilon)}]$

you can check that $\mu_+ = 1/\mu_-$ so that
attraction over W^s : $(\mu_-)^n$ or balance
with repulsion over W^u : $(\mu_+)^n$.

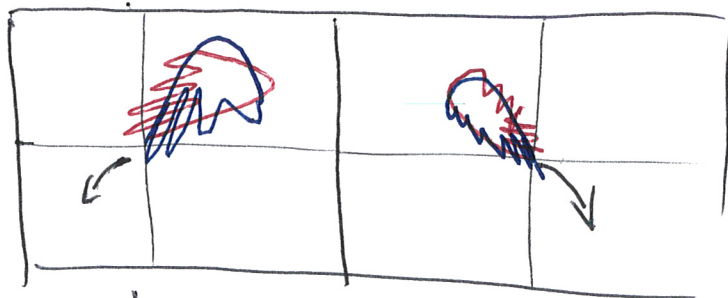
$\therefore$ SADDLE.

2 qualitative $\neq$ case for phase portrait

$D < 0$



$D > 0$



$\lambda > 0$

* Show pics from my PAPER #59

#31 + #56